


# SCI Block Guide V05.01

**Original Release Date: 29 Oct 2001**  
**Revised: 16 Apr 2004**

**8/16 Bit Division, TSPG**  
**Motorola, Inc.**

Motorola reserves the right to make changes without further notice to any products herein. Motorola makes no warranty, representation or guarantee regarding the suitability of its products for any particular purpose, nor does Motorola assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation consequential or incidental damages. "Typical" parameters which may be provided in Motorola data sheets and/or specifications can and do vary in different applications and actual performance may vary over time. All operating parameters, including "Typicals" must be validated for each customer application by customer's technical experts. Motorola does not convey any license under its patent rights nor the rights of others. Motorola products are not designed, intended, or authorized for use as components in systems intended for surgical implant into the body, or other applications intended to support or sustain life, or for any other application in which the failure of the Motorola product could create a situation where personal injury or death may occur. Should Buyer purchase or use Motorola products for any such unintended or unauthorized application, Buyer shall indemnify and hold Motorola and its officers, employees, subsidiaries, affiliates, and distributors harmless against all claims, costs, damages, and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if such claim alleges that Motorola was negligent regarding the design or manufacture of the part. Motorola and  are registered trademarks of Motorola, Inc. Motorola, Inc. is an Equal Opportunity/Affirmative Action Employer.

©Motorola, Inc., 2001

## Revision History

Version Number	Revision Date	Effective Date	Author	Description of Changes
00.10	06/04/1999			Original draft. Distributed only within Motorola
00.10	06/04/1999			Original draft. Distributed only within Motorola
00.20	09/01/1999			Specifications modified for Barracuda SCI. Changes based on change request.
00.30	09/20/1999			Specification updated after review at Munich
00.40	10/22/1999			Specification updated after changes in the number of interrupt signals from SCI
00.50	01/25/2000			Specification document updated after internal Design database review.
00.60	02/01/2000			TXDIR bit shifted from register SCIDRH (bit 0) to register SCISR2 (bit 1).
02.00	10/19/2000			BRK13 bit included in the SCISR2 (bit 3)
02.01	04/02/2001			Updated according to feedback concerning SRS v2 and additional rules compliance
02.02	07/19/2001			Document names have been added Names and Variable definitions have been hidden
02.03	10/10/2001			Correct the RWU definition in the SCI CR2 register and replace the STAR12 by HCS12.
03.00	10/29/2001			Added infrared encode and decode capability
03.01	03/12/2002			New document numbering. Corrected typos. Removed document order number except from Cover Sheet
03.02	07/03/2002			Added notes about IrDA standard, The IrDA standard referenced issued was v1.4 Removed the statement about baud rate generation error caused by synchronization (section 4.4), which does not exist in s12 Added test bit info (section 3.3.7, in conditional text); Inverted the Infrared polarity Added description of RZI data format in Infrared mode Removed the detail implementation description of Infrared receive decoder while added edge jitter information in section 4.2.2
04.00	07/30/2002			Added two polarity configure bits to control the polarity of transmit data and receive data respectively; Added 1/4 pulse width option for TNP[1:0]=11 in SCIBDRH register.

Version Number	Revision Date	Effective Date	Author	Description of Changes
05.00	06/02/2003			<p>Opened three new registers using a Mode bit.  Added Wakeup capability on Receive Input  Added LIN transmit collision detect capability  Added LIN break detect capability;</p> <p>Updated block diagram  Updated Table 4-3 to use more general bus clock frequency  Updated to be SRS3.0 compliant</p>
05.01	04/16/2004			<p>Update OR and PF flag description; Correct baud rate tolerance in 4.7.5.1 and 4.7.5.2; Clean up classification and NDA message banners</p>



## Section 1 Introduction

1.1	Overview . . . . .	11
1.2	Features . . . . .	11
1.3	Modes of Operation . . . . .	12

## Section 2 Signal Description

2.1	Overview . . . . .	13
2.2	Detailed Signal Descriptions . . . . .	13
2.2.1	TXD - SCI Transmit Pin . . . . .	13
2.2.2	RXD - SCI Receive Pin . . . . .	13

## Section 3 Memory Map and Registers

3.1	Overview . . . . .	14
3.2	Module Memory Map . . . . .	14
3.3	Register Descriptions . . . . .	15
3.3.1	SCI Baud Rate Registers (SCIBDH, SCIBDL) . . . . .	16
3.3.2	SCI Control Register 1 (SCICR1) . . . . .	17
3.3.3	SCI Alternative Status Register 1 (SCIASR1) . . . . .	19
3.3.4	SCI Alternative Control Register 1 (SCIACR1) . . . . .	20
3.3.5	SCI Alternative Control Register 2 (SCIACR2) . . . . .	20
3.3.6	SCI Control Register 2 (SCICR2) . . . . .	21
3.3.7	SCI Status Register 1 (SCISR1) . . . . .	22
3.3.8	SCI Status Register 2 (SCISR2) . . . . .	25
3.3.9	SCI Data Registers (SCIDRH, SCIDRL) . . . . .	26

## Section 4 Functional Description

4.1	General . . . . .	27
4.2	Infrared Interface Submodule . . . . .	28
4.2.1	Infrared Transmit Encoder . . . . .	29
4.2.2	Infrared Receive Decoder . . . . .	29
4.3	LIN Support . . . . .	29
4.4	Data Format . . . . .	29
4.5	Baud Rate Generation . . . . .	31
4.6	Transmitter . . . . .	32
4.6.1	Transmitter Character Length . . . . .	32
4.6.2	Character Transmission . . . . .	32

4.6.3	Break Characters . . . . .	34
4.6.4	Idle Characters . . . . .	35
4.6.5	LIN Transmit Collision Detection . . . . .	35
4.7	Receiver . . . . .	37
4.7.1	Receiver Character Length . . . . .	37
4.7.2	Character Reception . . . . .	37
4.7.3	Data Sampling . . . . .	38
4.7.4	Framing Errors . . . . .	42
4.7.5	Baud Rate Tolerance . . . . .	42
4.7.5.1	Slow Data Tolerance . . . . .	43
4.7.5.2	Fast Data Tolerance . . . . .	44
4.7.6	Receiver Wakeup . . . . .	44
4.7.6.1	Idle input line wakeup (WAKE = 0) . . . . .	45
4.7.6.2	Address mark wakeup (WAKE = 1) . . . . .	45
4.8	Single-Wire Operation . . . . .	45
4.9	Loop Operation . . . . .	46

## Section 5 Initialization/Application Information

5.1	Reset Initialization . . . . .	47
5.2	Modes of Operation . . . . .	47
5.2.1	Run Mode . . . . .	47
5.2.2	Wait Mode . . . . .	47
5.2.3	Stop Mode . . . . .	47
5.3	Interrupt Operation . . . . .	47
5.3.1	General . . . . .	47
5.3.2	Description of Interrupt Operation . . . . .	48
5.3.2.1	TDRE Description . . . . .	48
5.3.2.2	TC Description . . . . .	48
5.3.2.3	RDRF Description . . . . .	49
5.3.2.4	OR Description . . . . .	49
5.3.2.5	IDLE Description . . . . .	49
5.3.2.6	RXEDGIF Description . . . . .	49
5.3.2.7	BERRIF Description . . . . .	49
5.3.2.8	BKDIF Description . . . . .	49
5.3.3	Recovery from Wait Mode . . . . .	49
5.3.4	Recovery from STOP mode . . . . .	49

Figure 1-1	SCI Block Diagram . . . . .	11
Figure 3-1	SCI Register Quick Reference. . . . .	15
Figure 3-2	SCI Baud Rate Registers (SCI BDH/L) . . . . .	16
Figure 3-3	SCI Control Register 1 (SCICR1) . . . . .	17
Figure 3-4	SCI Alternative Status Register 1 (SCIASR1) . . . . .	19
Figure 3-5	SCI Alternative Control Register 1 (SCIACR1) . . . . .	20
Figure 3-6	SCI Alternative Control Register 2 (SCIACR2) . . . . .	20
Figure 3-7	SCI Control Register 2 (SCICR2) . . . . .	21
Figure 3-8	SCI Status Register 1 (SCISR1) . . . . .	23
Figure 3-9	SCI Status Register 2 (SCISR2) . . . . .	25
Figure 3-10	SCI Data Registers (SCIDRH/L) . . . . .	26
Figure 4-1	Detailed SCI Block Diagram . . . . .	28
Figure 4-2	SCI Data Formats . . . . .	30
Figure 4-3	Transmitter Block Diagram . . . . .	32
Figure 4-4	Collision Detect Principle. . . . .	35
Figure 4-5	Timing Diagram Bit Error Detection. . . . .	36
Figure 4-6	SCI Receiver Block Diagram. . . . .	37
Figure 4-7	Receiver Data Sampling . . . . .	38
Figure 4-8	Start Bit Search Example 1 . . . . .	40
Figure 4-9	Start Bit Search Example 2 . . . . .	40
Figure 4-10	Start Bit Search Example 3 . . . . .	41
Figure 4-11	Start Bit Search Example 4 . . . . .	41
Figure 4-12	Start Bit Search Example 5 . . . . .	42
Figure 4-13	Start Bit Search Example 6 . . . . .	42
Figure 4-14	Slow Data . . . . .	43
Figure 4-15	Fast Data . . . . .	44





Table 3-1	Module Memory Map . . . . .	14
Table 3-2	IRSCI Transmit Pulse Width . . . . .	16
Table 3-3	Loop Functions . . . . .	18
Table 3-4	Bit Error Mode Coding . . . . .	21
Table 4-2	Example of 9-Bit Data Formats . . . . .	30
Table 4-1	Example of 8-bit Data Formats . . . . .	30
Table 4-3	Baud Rates (Example: Module Clock = 25 Mhz) . . . . .	31
Table 4-4	Start Bit Verification . . . . .	38
Table 4-5	Data Bit Recovery . . . . .	39
Table 4-6	Stop Bit Recovery . . . . .	39
Table 5-1	SCI Interrupt Sources . . . . .	48



# Preface

The SCI allows full duplex, asynchronous, serial communication between the CPU and remote devices, including other CPUs. The SCI transmitter and receiver operate independently, although they use the same baud rate generator. The CPU monitors the status of the SCI, writes the data to be transmitted, and processes received data.

## Terminology

IR: InfraRed

IrDA: Infrared Design Associate

IRQ: Interrupt Request

LIN: Local Interconnect Network

LSB: Least Significant Bit

MSB: Most Significant Bit

NRZ: Non-Return-to-Zero

RZI: Return-to-Zero-Inverted

RXD: Receive Pin

SCI : Serial Communication Interface

TXD: Transmit Pin



## Section 1 Introduction

This block guide provide an overview of Serial Communication Interface (SCI) module.

Figure 1-1 is a high level block diagram of the SCI module, showing the interaction of various function blocks.

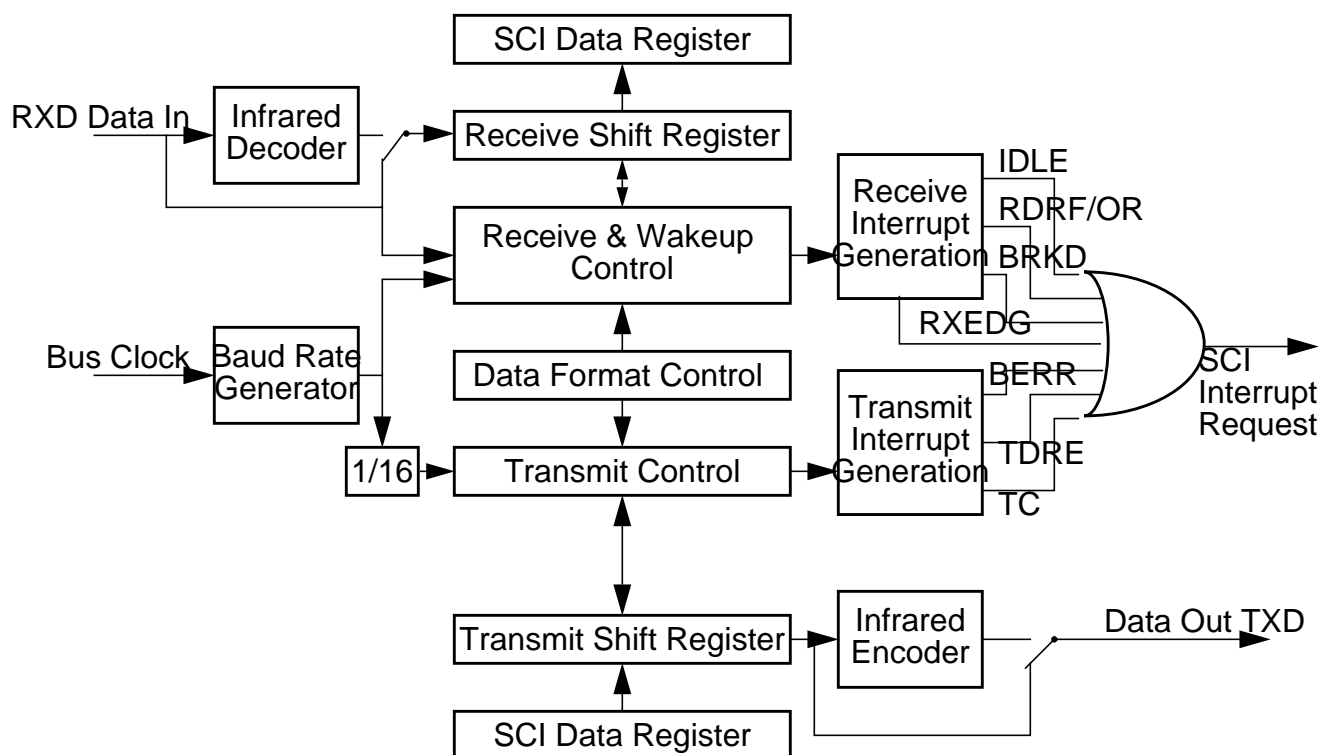


Figure 1-1 SCI Block Diagram

### 1.1 Overview

The SCI allows asynchronous serial communications with peripheral devices and other CPUs.

### 1.2 Features

The SCI includes these distinctive features:

- Full-duplex or single-wire operation
- Standard mark/space non-return-to-zero (NRZ) format
- Selectable IrDA 1.4 return-to-zero-inverted (RZI) format with programmable pulse widths

- 13-bit baud rate selection
- Programmable 8-bit or 9-bit data format
- Separately enabled transmitter and receiver
- Programmable polarity for transmitter and receiver
- Programmable transmitter output parity
- Two receiver wakeup methods:
  - Idle line wakeup
  - Address mark wakeup
- Interrupt-driven operation with eight flags:
  - Transmitter empty
  - Transmission complete
  - Receiver full
  - Idle receiver input
  - Receiver overrun
  - Noise error
  - Framing error
  - Parity error
  - Receive wakeup on active edge
  - Transmit collision detect supporting LIN
  - Break Detect supporting LIN
- Receiver framing error detection
- Hardware parity checking
- 1/16 bit-time noise detection

## **1.3 Modes of Operation**

The SCI functions the same in normal, special, and emulation modes. It has two low power modes, wait and stop modes.

- Run Mode
- Wait Mode
- Stop Mode

## Section 2 Signal Description

### 2.1 Overview

The SCI module has a total of 2 external pins.

### 2.2 Detailed Signal Descriptions

#### 2.2.1 TXD - SCI Transmit Pin

The TXD pin transmits SCI (standard or infrared) data. It will idle high in either mode and is high impedance anytime the transmitter is disabled.

#### 2.2.2 RXD - SCI Receive Pin

The RXD pin receives SCI (standard or infrared) data. An idle line is detected as a line high. This input is ignored when the receiver is disabled and should be terminated to a known voltage.

## Section 3 Memory Map and Registers

### 3.1 Overview

This section provides a detailed description of all the SCI registers.

### 3.2 Module Memory Map

The memory map for the SCI module is given below in **Table 3-1**. The Address listed for each register is the address offset. The total address for each register is the sum of the base address for the SCI module and the address offset for each register.

**Table 3-1 Module Memory Map**

Offset	Name	Access
\$_0 <sup>1</sup>	SCI Baud Rate Register High (SCIBDH)	Read/Write
\$_1 <sup>1</sup>	SCI Baud Rate Register Low (SCIBDL)	Read/Write
\$_2 <sup>1</sup>	SCI Control Register1 (SCICR1)	Read/Write
\$_0a <sup>2</sup>	SCI Alternative Status Register 1 (SCIASR1)	Read/Write
\$_1a <sup>2</sup>	SCI Alternative Control Register 1 (SCIACR1)	Read/Write
\$_2a <sup>2</sup>	SCI Alternative Control Register 2 (SCIACR2)	Read/Write
\$_3	SCI Control Register 2 (SCICR2)	Read/Write
\$_4	SCI Status Register 1 (SCISR1)	Read
\$_5	SCI Status Register 2(SCISR2)	Read/Write
\$_6	SCI Data Register High (SCIDRH)	Read/Write
\$_7	SCI Data Register Low (SCIDRL)	Read/Write

NOTES:

1. Those registers are accessible if the AMAP bit in the SCISR2 register is set to zero
2. Those registers are accessible if the AMAP bit in the SCISR2 register is set to one



## Register Quick Reference

Register name		Bit 7	6	5	4	3	2	1	Bit 0	Addr. offset
SCIBDH <sup>1</sup>	Read:	IREN	TNP1	TNP0	SBR12	SBR11	SBR10	SBR9	SBR8	\$_0
	Write:									
SCIBDL <sup>1</sup>	Read:	SBR7	SBR6	SBR5	SBR4	SBR3	SBR2	SBR1	SBR0	\$_1
	Write:									
SCICR1 <sup>1</sup>	Read:	LOOPS	SCISWAI	RSRC	M	WAKE	ILT	PE	PT	\$_2
	Write:									
SCIASR1 <sup>2</sup>	Read:	RXEDGIF	0	0	0	0	BERRV	BERRIF	BKDIF	\$_0a
	Write:									
SCIACR1 <sup>2</sup>	Read:	RXEDGIE	0	0	0	0	0	BERRIE	BKDIE	\$_1a
	Write:									
SCIACR2 <sup>2</sup>	Read:	0	0	0	0	0	BERRM1	BERRM0	BKDFE	\$_2a
	Write:									
SCICR2	Read:	TIE	TCIE	RIE	ILIE	TE	RE	RWU	SBK	\$_3
	Write:									
SCISR1	Read:	TDRE	TC	RDRF	IDLE	OR	NF	FE	PF	\$_4
	Write:									
SCISR2	Read:	AMAP	0	0	TXPOL	RXPOL	BRK13	TXDIR	RAF	\$_5
	Write:									
SCIDRH	Read:	R8	T8	0	0	0	0	0	0	\$_6
	Write:									
SCIDRL	Read:	R7	R6	R5	R4	R3	R2	R1	R0	\$_7
	Write:	T7	T6	T5	T4	T3	T2	T1	T0	

 = Reserved or unimplemented

### NOTES:

- Those registers are accessible if the AMAP bit in the SCISR2 register is set to zero
- Those registers are accessible if the AMAP bit in the SCISR2 register is set to one

**Figure 3-1 SCI Register Quick Reference**

## 3.3 Register Descriptions

This section consists of register descriptions in address order. Each description includes a standard register diagram with an associated figure number. Writes to a reserved register locations do not have any effect and reads of these locations return a zero. Details of register bit and field function follow the register diagrams, in bit order.

3.3.1 SCI Baud Rate Registers (SCIBDH, SCIBDL)

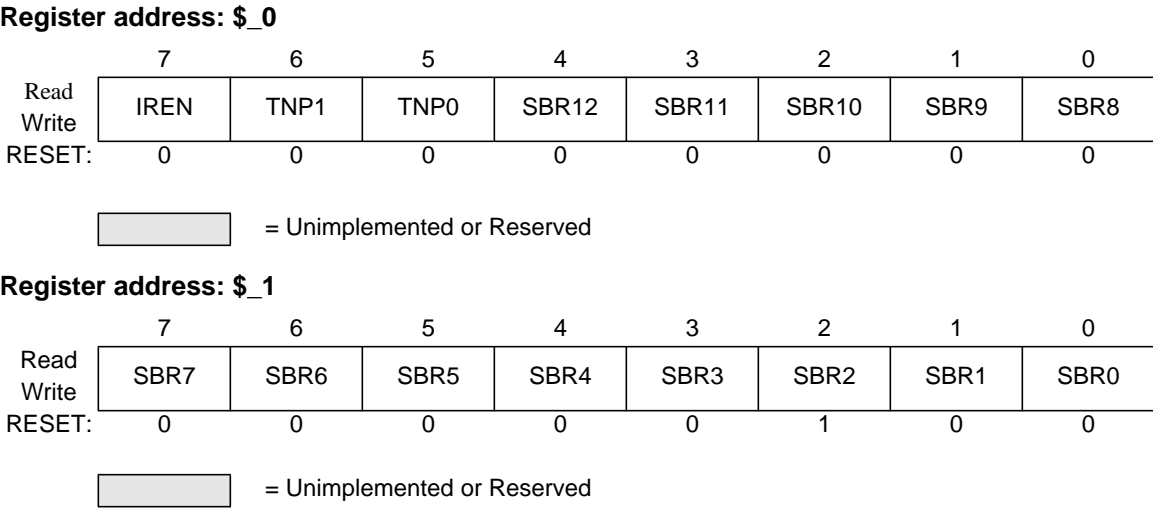


Figure 3-2 SCI Baud Rate Registers (SCI BDH/L)

Read: anytime, if AMAP = 0. If only SCIBDH is written to, a read will not return the correct data until SCIBDL is written to as well, following a write to SCIBDH.

Write: anytime, if AMAP = 0.

Attention: Those two registers are only visible in the memory map if AMAP = 0 (reset condition).

The SCI Baud Rate Register is used by to determine the baud rate of the SCI, and to control the infrared modulation/demodulation submodule.

IREN — Infrared Enable Bit

This bit enables/disables the infrared modulation/demodulation submodule.

- 1 = IR enabled
- 0 = IR disabled

TNP1,TNP0 - Transmitter Narrow Pulse Bits

These bits enable whether the SCI transmits a 1/16, 3/16, 1/32 or 1/4 narrow pulse.

Table 3-2 IRSCI Transmit Pulse Width

TNP[1:0]	Narrow Pulse Width
11	1/4
10	1/32
01	1/16
00	3/16

SBR[12:0] - SCI Baud Rate Bits

The baud rate for the SCI is determined by the bits in this register. The baud rate is calculated two different ways depending on the state of the IREN bit.

The formulas for calculating the baud rate are:

When IREN=0 then,

$$\text{SCI baud rate} = \text{SCI bus clock} / (16 \times \text{SBR}[12:0])$$

When IREN=1 then,

$$\text{SCI baud rate} = \text{SCI bus clock} / (32 \times \text{SBR}[12:1])$$


**NOTE:** The baud rate generator is disabled after reset and not started until the TE bit or the RE bit is set for the first time. The baud rate generator is disabled when ( $\text{SBR}[12:0] = 0$  and  $\text{IREN} = 0$ ) or ( $\text{SBR}[12:1] = 0$  and  $\text{IREN} = 1$ ).

**NOTE:** Writing to SCIBDH has no effect without writing to SCIBDL, since writing to SCIBDH puts the data in a temporary location until SCIBDL is written to.

### 3.3.2 SCI Control Register 1 (SCICR1)

Register address: \$\_2

	7	6	5	4	3	2	1	0
Read	LOOPS	SCISWAI	RSRC	M	WAKE	ILT	PE	PT
Write								
RESET:	0	0	0	0	0	0	0	0

 = Unimplemented or Reserved

**Figure 3-3 SCI Control Register 1 (SCICR1)**

Read: anytime, if AMAP = 0.

Write: anytime, if AMAP = 0.

Attention: This register is only visible in the memory map if AMAP = 0 (reset condition).

**LOOPS** - Loop Select Bit

LOOPS enables loop operation. In loop operation, the RXD pin is disconnected from the SCI and the transmitter output is internally connected to the receiver input. Both the transmitter and the receiver must be enabled to use the loop function.

1 = Loop operation enabled

0 = Normal operation enabled

The receiver input is determined by the RSRC bit.

**SCISWAI — SCI Stop in Wait Mode Bit**

SCISWAI disables the SCI in wait mode.

- 1 = SCI disabled in wait mode
- 0 = SCI enabled in wait mode

**RSRC — Receiver Source Bit**

When LOOPS = 1, the RSRC bit determines the source for the receiver shift register input.

- 1 = Receiver input connected externally to transmitter
- 0 = Receiver input internally connected to transmitter output

**Table 3-3 Loop Functions**

LOOPS	RSRC	Function
0	x	Normal operation
1	0	Loop mode with transmitter output internally connected to receiver input
1	1	Single-wire mode with TXD pin connected to receiver input

**M — Data Format Mode Bit**

MODE determines whether data characters are eight or nine bits long.

- 1 = One start bit, nine data bits, one stop bit
- 0 = One start bit, eight data bits, one stop bit

**WAKE — Wakeup Condition Bit**

WAKE determines which condition wakes up the SCI: a logic 1 (address mark) in the most significant bit position of a received data character or an idle condition on the RXD pin.

- 1 = Address mark wakeup
- 0 = Idle line wakeup

**ILT — Idle Line Type Bit**

ILT determines when the receiver starts counting logic 1s as idle character bits. The counting begins either after the start bit or after the stop bit. If the count begins after the start bit, then a string of logic 1s preceding the stop bit may cause false recognition of an idle character. Beginning the count after the stop bit avoids false idle character recognition, but requires properly synchronized transmissions.

- 1 = Idle character bit count begins after stop bit
- 0 = Idle character bit count begins after start bit

**PE — Parity Enable Bit**

PE enables the parity function. When enabled, the parity function inserts a parity bit in the most significant bit position.

- 1 = Parity function enabled
- 0 = Parity function disabled

**PT — Parity Type Bit**


PT determines whether the SCI generates and checks for even parity or odd parity. With even parity, an even number of 1s clears the parity bit and an odd number of 1s sets the parity bit. With odd parity, an odd number of 1s clears the parity bit and an even number of 1s sets the parity bit.

1 = Odd parity  
0 = Even parity

### 3.3.3 SCI Alternative Status Register 1 (SCIASR1)

Register address: `$_0a`

	7	6	5	4	3	2	1	0
Read	RXEDGIF	0	0	0	0	BERRV	BERRIF	BKDIF
Write								
RESET:	0	0	0	0	0	0	0	0

 = Unimplemented or Reserved

**Figure 3-4 SCI Alternative Status Register 1 (SCIASR1)**

Read: anytime, if AMAP = 1

Write: anytime, if AMAP = 1

**RXEDGIF** — Receive Input Active Edge Interrupt Flag

RXEDGIF is asserted, if an active edge (falling if RXPOL = 0, rising if RXPOL = 1) on the RXD input occurs. RXEDGIF bit is cleared by writing a “1” to it.

1 = An active edge on the receive input has occurred  
0 = No active receive on the receive input has occurred

**BERRV** — Bit Error Value

BERRV reflects the state of the RXD input when the bit error detect circuitry is enabled and a mismatch to the expected value happened. The value is only meaningful, if BERRIF = 1.

1 = A high input reassembled, when a low was expected  
0 = A low input was sampled, when a high was expected

**BERRIF** — Bit Error Interrupt Flag

BERRIF is asserted, when the bit error detect circuitry is enabled and if the value sampled at the RXD input does not match the transmitted value. If the BERRIE interrupt enable bit is set an interrupt will be generated. The BERRIF bit is cleared by writing a “1” to it.

1 = A mismatch has occurred  
0 = No mismatch detected

**BKDIF** — Break Detect Interrupt Flag


BKDIF is asserted, if the break detect circuitry is enabled and a break signal is received. If the BKDIE interrupt enable bit is set an interrupt will be generated. The BKDIF bit is cleared by writing a “1” to it.

1 = A break signal was received  
0 = No break signal was received

### 3.3.4 SCI Alternative Control Register 1 (SCIACR1)

Register address:  $\$_{1a}$

	7	6	5	4	3	2	1	0
Read	RXEDGIE	0	0	0	0	0	BERRIE	BKDIE
Write								
RESET:	0	0	0	0	0	0	0	0

 = Unimplemented or Reserved

**Figure 3-5 SCI Alternative Control Register 1 (SCIACR1)**

Read: anytime, if AMAP = 1

Write: anytime, if AMAP = 1

**RXEDGIE** — Receive Input Active Edge Interrupt Enable

RXEDGIE enables the Receive Input Active Edge Interrupt Flag, RXEDGIF, to generate interrupt requests.

1 = RXEDGIF interrupt requests enabled

0 = RXEDGIF interrupt requests disabled

**BERRIE** — Bit Error Interrupt Enable

BERRIE enables the Bit Error Interrupt Flag, BERRIF, to generate interrupt requests.

1 = BERRIF interrupt requests enabled

0 = BERRIF interrupt requests disabled

**BKDIE** — Break Detect Interrupt Enable

BKDIE enables the Break Detect Interrupt Flag, BKDIF, to generate interrupt requests.

1 = BKDIF interrupt requests enabled

0 = BKDIF interrupt requests disabled

### 3.3.5 SCI Alternative Control Register 2 (SCIACR2)

Register address:  $\$_{2a}$

	7	6	5	4	3	2	1	0
Read	0	0	0	0	0	BERRM1	BERRM0	BKDFE
Write								
RESET:	0	0	0	0	0	0	0	0

 = Unimplemented or Reserved

**Figure 3-6 SCI Alternative Control Register 2 (SCIACR2)**

Read: anytime, if AMAP = 1

Write: anytime, if AMAP = 1

#### BERRM[1:0] — Bit Error Mode

Those two bits determines the functionality of the Bit Error Detect Feature.

**Table 3-4 Bit Error Mode Coding**

BERRM1	BERRM0	Function
0	0	Bit Error detect circuit is disabled
0	1	Receive input sampling occurs during the 9th time tick of a transmitted bit (refer to <b>Figure 4-6</b> )
1	0	Receive input sampling occurs during the 13th time tick of a transmitted bit (refer to <b>Figure 4-6</b> )
1	1	Reserved

#### BKDFE — Break Detect Feature Enable

BKDFE enables the Break Detect Circuitry.

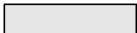
1 = Break Detect Circuit enabled

0 = Break Detect Circuit disabled

### 3.3.6 SCI Control Register 2 (SCICR2)

Register address: **\$\_3**

	7	6	5	4	3	2	1	0
Read	TIE	TCIE	RIE	ILIE	TE	RE	RWU	SBK
Write								
RESET:	0	0	0	0	0	0	0	0

 = Unimplemented or Reserved

**Figure 3-7 SCI Control Register 2 (SCICR2)**

Read: anytime

Write: anytime

#### TIE — Transmitter Interrupt Enable Bit

TIE enables the transmit data register empty flag, TDRE, to generate interrupt requests.

1 = TDRE interrupt requests enabled

0 = TDRE interrupt requests disabled

#### TCIE — Transmission Complete Interrupt Enable Bit

TCIE enables the transmission complete flag, TC, to generate interrupt requests.

1 = TC interrupt requests enabled

0 = TC interrupt requests disabled

#### RIE — Receiver Full Interrupt Enable Bit

RIE enables the receive data register full flag, RDRF, or the overrun flag, OR, to generate interrupt requests.

- 1 = RDRF and OR interrupt requests enabled
- 0 = RDRF and OR interrupt requests disabled

**ILIE — Idle Line Interrupt Enable Bit**

ILIE enables the idle line flag, IDLE, to generate interrupt requests.

- 1 = IDLE interrupt requests enabled
- 0 = IDLE interrupt requests disabled

**TE — Transmitter Enable Bit**

TE enables the SCI transmitter and configures the TXD pin as being controlled by the SCI. The TE bit can be used to queue an idle preamble.

- 1 = Transmitter enabled
- 0 = Transmitter disabled

**RE — Receiver Enable Bit**

RE enables the SCI receiver.

- 1 = Receiver enabled
- 0 = Receiver disabled

**RWU — Receiver Wakeup Bit**

Standby state

- 1 = RWU enables the wakeup function and inhibits further receiver interrupt requests. Normally, hardware wakes the receiver by automatically clearing RWU.
- 0 = Normal operation.

**SBK — Send Break Bit**

Toggling SBK sends one break character (10 or 11 logic 0s, respectively 13 or 14 logic 0s if BRK13 is set). Toggling implies clearing the SBK bit before the break character has finished transmitting. As long as SBK is set, the transmitter continues to send complete break characters (10 or 11 bits, respectively 13 or 14 bits).

- 1 = Transmit break characters
- 0 = No break characters

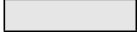
### **3.3.7 SCI Status Register 1 (SCISR1)**

The SCISR1 and SCISR2 registers provides inputs to the MCU for generation of SCI interrupts. Also, these registers can be polled by the MCU to check the status of these bits. The flag-clearing procedures require that the status register be read followed by a read or write to the SCI Data Register. It is permissible to execute other instructions between the two steps as long as it does not compromise the handling of I/O, but the order of operations is important for flag clearing.



Register address: \$\_4

	7	6	5	4	3	2	1	0
Read	TDRE	TC	RDRF	IDLE	OR	NF	FE	PF
Write								
RESET:	1	1	0	0	0	0	0	0

 = Unimplemented or Reserved

**Figure 3-8 SCI Status Register 1 (SCISR1)**

Read: anytime

Write: has no meaning or effect

**TDRE — Transmit Data Register Empty Flag**

TDRE is set when the transmit shift register receives a byte from the SCI data register. When TDRE is 1, the transmit data register (SCIDRH/L) is empty and can receive a new value to transmit. Clear TDRE by reading SCI status register 1 (SCISR1), with TDRE set and then writing to SCI data register low (SCIDRL).

1 = Byte transferred to transmit shift register; transmit data register empty

0 = No byte transferred to transmit shift register

**TC — Transmit Complete Flag**

TC is set low when there is a transmission in progress or when a preamble or break character is loaded. TC is set high when the TDRE flag is set and no data, preamble, or break character is being transmitted. When TC is set, the TXD pin becomes idle (logic 1). Clear TC by reading SCI status register 1 (SCISR1) with TC set and then writing to SCI data register low (SCIDRL). TC is cleared automatically when data, preamble, or break is queued and ready to be sent. TC is cleared in the event of a simultaneous set and clear of the TC flag (transmission not complete).

1 = No transmission in progress

0 = Transmission in progress

**RDRF — Receive Data Register Full Flag**

RDRF is set when the data in the receive shift register transfers to the SCI data register. Clear RDRF by reading SCI status register 1 (SCISR1) with RDRF set and then reading SCI data register low (SCIDRL).

1 = Received data available in SCI data register

0 = Data not available in SCI data register

**IDLE — Idle Line Flag**

IDLE is set when 10 consecutive logic 1s (if M=0) or 11 consecutive logic 1s (if M=1) appear on the receiver input. Once the IDLE flag is cleared, a valid frame must again set the RDRF flag before an idle condition can set the IDLE flag. Clear IDLE by reading SCI status register 1 (SCISR1) with IDLE set and then reading SCI data register low (SCIDRL).

1 = Receiver input has become idle

0 = Receiver input is either active now or has never become active since the IDLE flag was last cleared

**NOTE:** *When the receiver wakeup bit (RWU) is set, an idle line condition does not set the IDLE flag.*

#### OR — Overrun Flag

OR is set when software fails to read the SCI data register before the receive shift register receives the next frame. The OR bit is set immediately after the stop bit has been completely received for the second frame. The data in the shift register is lost, but the data already in the SCI data registers is not affected. Clear OR by reading SCI status register 1 (SCISR1) with OR set and then reading SCI data register low (SCIDRL).

1 = Overrun

0 = No overrun

**NOTE:** *OR flag may read back as set when RDRF flag is clear. This may happen if the following sequence of events occurs:*

- 1. After the first frame is received, read status register SCISR1 (returns RDRF set and OR flag clear);*
- 2. Receive second frame without reading the first frame in the data register (the second frame is not received and OR flag is set);*
- 3. Read data register SCIDRL (returns first frame and clears RDRF flag in the status register);*
- 4. read status register SCISR1 (returns RDRF clear and OR set).*

*Event 3 may be at exactly the same time as event 2 or any time after. When this happens, a dummy SCIDRL read following event 4 will be required to clear the OR flag if further frames are to be received.*

#### NF — Noise Flag

NF is set when the SCI detects noise on the receiver input. NF bit is set during the same cycle as the RDRF flag but does not get set in the case of an overrun. Clear NF by reading SCI status register 1 (SCISR1), and then reading SCI data register low (SCIDRL).

1 = Noise

0 = No noise

#### FE — Framing Error Flag

FE is set when a logic 0 is accepted as the stop bit. FE bit is set during the same cycle as the RDRF flag but does not get set in the case of an overrun. FE inhibits further data reception until it is cleared. Clear FE by reading SCI status register 1 (SCISR1) with FE set and then reading the SCI data register low (SCIDRL).

1 = Framing error

0 = No framing error

#### PF — Parity Error Flag

PF is set when the parity enable bit (PE) is set and the parity of the received data does not match the parity type bit (PT). PF bit is set during the same cycle as the RDRF flag but does not get set in the case of an overrun. Clear PF by reading SCI status register 1 (SCISR1), and then reading SCI data register low (SCIDRL).


1 = Parity error

0 = No parity error

### 3.3.8 SCI Status Register 2 (SCISR2)

Register address: **\$\_5**

	7	6	5	4	3	2	1	0
Read	AMAP	0	0	TXPOL	RXPOL	BRK13	TXDIR	RAF
Write								
RESET:	0	0	0	0	0	0	0	0

 = Unimplemented or Reserved

**Figure 3-9 SCI Status Register 2 (SCISR2)**

Read: anytime

Write: anytime;

#### AMAP — Alternative Map

This bit controls which registers sharing the same address space are accessible. In the reset condition the SCI behaves as previous versions. Setting AMAP=1 allows the access to another set of control and status registers and hides the baud rate and SCI control Register 1.

1 = The registers labelled SCIASR1 (\$\_0a), SCIACR1 (\$\_1a), SCIACR2 (\$02a) are accessible

0 = The registers labelled SCIBDH (\$\_0), SCIBDL (\$\_1), SCICR1 (\$02) are accessible

#### TXPOL — Transmit Polarity

This bit control the polarity of the transmitted data. In NRZ format, a one is represented by a mark and a zero is represented by a space for normal polarity, and the opposite for inverted polarity. In IrDA format, a zero is represented by short high pulse in the middle of a bit time remaining idle low for a one for normal polarity, and a zero is represented by short low pulse in the middle of a bit time remaining idle high for a one for inverted polarity.

1 = Inverted polarity

0 = Normal polarity

#### RXPOL — Receive Polarity

This bit control the polarity of the received data. In NRZ format, a one is represented by a mark and a zero is represented by a space for normal polarity, and the opposite for inverted polarity. In IrDA format, a zero is represented by short high pulse in the middle of a bit time remaining idle low for a one for normal polarity, and a zero is represented by short low pulse in the middle of a bit time remaining idle high for a one for inverted polarity.

- 1 = Inverted polarity
- 0 = Normal polarity

BRK13 — Break Transmit character length

This bit determines whether the transmit break character is 10 or 11 bit respectively 13 or 14 bits long. The detection of a framing error is not affected by this bit.

- 1 = Break character is 13 or 14 bit long
- 0 = Break Character is 10 or 11 bit long

TXDIR — Transmitter pin data direction in Single-Wire mode.

This bit determines whether the TXD pin is going to be used as an input or output, in the Single-Wire mode of operation. This bit is only relevant in the Single-Wire mode of operation.

- 1 = TXD pin to be used as an output in Single-Wire mode
- 0 = TXD pin to be used as an input in Single-Wire mode

RAF — Receiver Active Flag

RAF is set when the receiver detects a logic 0 during the RT1 time period of the start bit search. RAF is cleared when the receiver detects an idle character.

- 1 = Reception in progress
- 0 = No reception in progress

3.3.9 SCI Data Registers (SCIDRH, SCIDRL)

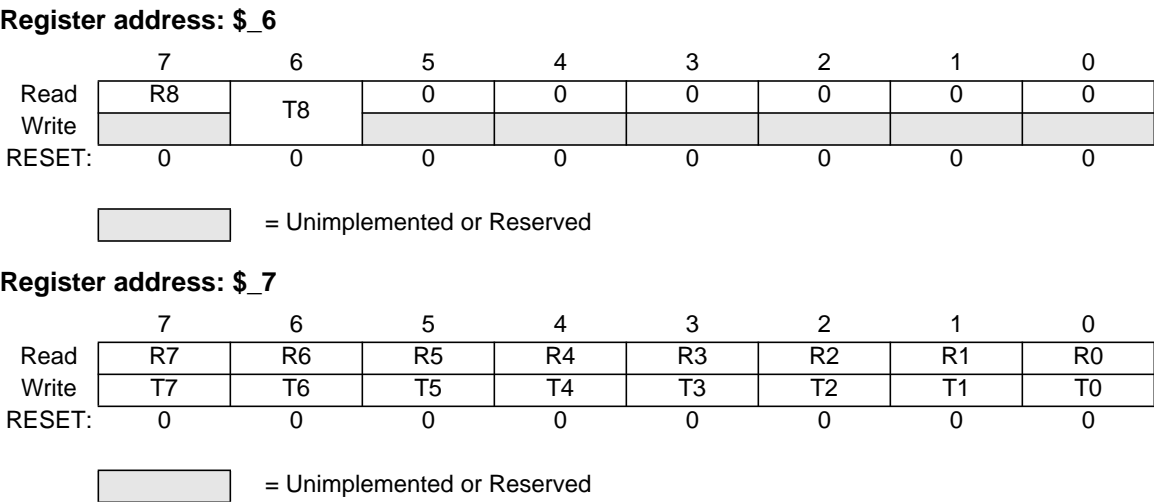


Figure 3-10 SCI Data Registers (SCIDRH/L)

Read: anytime; reading accesses SCI receive data register

Write: anytime; writing accesses SCI transmit data register; writing to R8 has no effect

R8 — Received Bit 8

R8 is the ninth data bit received when the SCI is configured for 9-bit data format ( $M = 1$ ).

T8 — Transmit Bit 8

T8 is the ninth data bit transmitted when the SCI is configured for 9-bit data format ( $M = 1$ ).

R7-R0 — Received bits seven through zero for 9-bit or 8-bit data formats

T7-T0 — Transmit bits seven through zero for 9-bit or 8-bit formats

**NOTE:** *If the value of T8 is the same as in the previous transmission, T8 does not have to be rewritten. The same value is transmitted until T8 is rewritten*

**NOTE:** *In 8-bit data format, only SCI data register low (SCIDRL) needs to be accessed.*

**NOTE:** *When transmitting in 9-bit data format and using 8-bit write instructions, write first to SCI data register high (SCIDRH), then SCIDRL.*

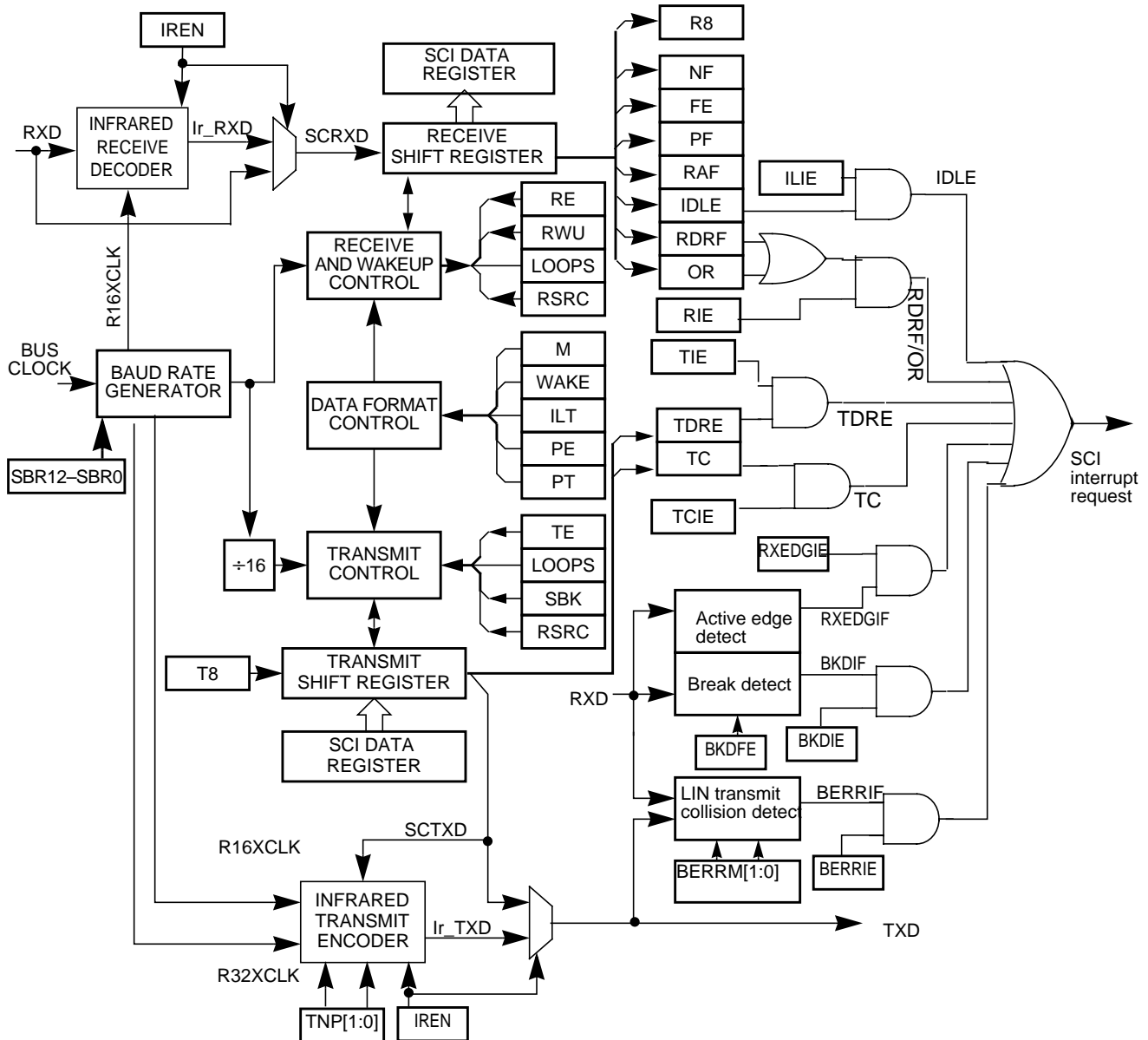
## Section 4 Functional Description

### 4.1 General

This section provides a complete functional description of the SCI block, detailing the operation of the design from the end user perspective in a number of subsections.

**Figure 4-1** shows the structure of the SCI module. The SCI allows full duplex, asynchronous, serial communication between the CPU and remote devices, including other CPUs. The SCI transmitter and receiver operate independently, although they use the same baud rate generator. The CPU monitors the status of the SCI, writes the data to be transmitted, and processes received data.

### Figure 4-1 Detailed SCI Block Diagram



## 4.2 Infrared Interface Submodule

This module provides the capability of transmitting narrow pulses to an IR LED and receiving narrow pulses and transforming them to serial bits, which are sent to the SCI. The IrDA physical layer specification defines a half-duplex infrared communication link for exchange data. The full standard includes data rates up to 16 Mbits/s. This design covers only data rates between 2.4 Kbits/s and 115.2 Kbits/s.

The infrared submodule consists of two major blocks: the transmit encoder and the receive decoder. The SCI transmits serial bits of data which are encoded by the infrared submodule to transmit a narrow pulse for every zero bit. No pulse is transmitted for every one bit. When receiving data, the IR pulses should be detected using an IR photo diode and transformed to CMOS levels by the IR receive decoder (external from the MCU). The narrow pulses are then stretched by the infrared submodule to get back to a serial bit stream to be received by the SCI. The polarity of transmitted pulses and expected receive pulses can be inverted so that a direct connection can be made to external IrDA transceiver modules that uses active low pulses.

The infrared submodule receives its clock sources from the SCI. One of these two clocks are selected in the infrared submodule in order to generate either 3/16, 1/16, 1/32 or 1/4 narrow pulses during transmission. The infrared block receives two clock sources from the SCI, R16XCLK and R32XCLK, which are configured to generate the narrow pulse width during transmission. The R16XCLK and R32XCLK are internal clocks with frequencies 16 and 32 times the baud rate respectively. Both R16XCLK and R32XCLK clocks are used for transmitting data. The receive decoder uses only the R16XCLK clock.

### 4.2.1 Infrared Transmit Encoder

The infrared transmit encoder converts serial bits of data from transmit shift register to the TXD pin. A narrow pulse is transmitted for a zero bit and no pulse for a one bit. The narrow pulse is sent in the middle of the bit with a duration of 1/32, 1/16, 3/16 or 1/4 of a bit time. A narrow high pulse is transmitted for a zero bit when TXPOL is cleared, while a narrow low pulse is transmitted for a zero bit when TXPOL is set.

### 4.2.2 Infrared Receive Decoder

The infrared receive block converts data from the RXD pin to the receive shift register. A narrow pulse is expected for each zero received and no pulse is expected for each one received. A narrow high pulse is expected for a zero bit when RXPOL is cleared, while a narrow low pulse is expected for a zero bit when RXPOL is set. This receive decoder meets the edge jitter requirement as defined by the IrDA serial infrared physical layer specification.

## 4.3 LIN Support

This module provides some basic support for the LIN protocol. At first this is a break detect circuitry making it easier for the LIN software to distinguish a break character from an incoming data stream. As a further addition it supports a collision detection at the bit level as well as cancelling pending transmissions.

## 4.4 Data Format

The SCI uses the standard NRZ mark/space data format. When Infrared is enabled, the SCI uses RZI data format where zeroes are represented by light pulses and ones remain low. See **Figure 4-2** below.

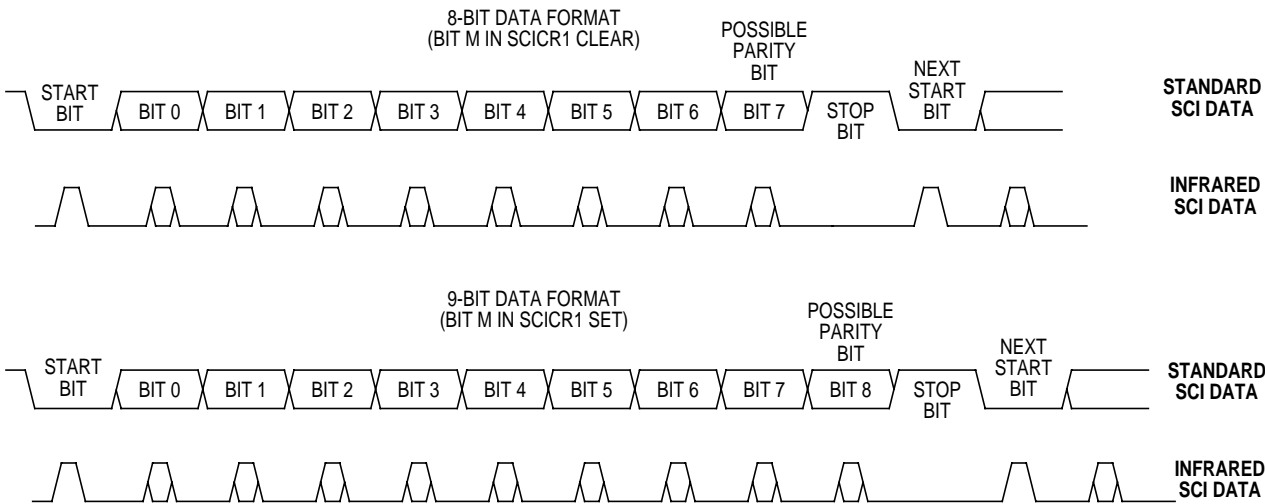


Figure 4-2 SCI Data Formats

Each data character is contained in a frame that includes a start bit, eight or nine data bits, and a stop bit. Clearing the M bit in SCI control register 1 configures the SCI for 8-bit data characters. A frame with eight data bits has a total of 10 bits. Setting the M bit configures the SCI for nine-bit data characters. A frame with nine data bits has a total of 11 bits

Table 4-1 Example of 8-bit Data Formats

Start Bit	Data Bits	Address Bits	Parity Bits	Stop Bit
1	8	0	0	1
1	7	0	1	1
1	7	1 <sup>1</sup>	0	1

NOTES:

1. The address bit identifies the frame as an address character. See section on Receiver Wakeup

When the SCI is configured for 9-bit data characters, the ninth data bit is the T8 bit in SCI data register high (SCIDRH). It remains unchanged after transmission and can be used repeatedly without rewriting it. A frame with nine data bits has a total of 11 bits.

Table 4-2 Example of 9-Bit Data Formats

Start Bit	Data Bits	Address Bits	Parity Bits	Stop Bit
1	9	0	0	1
1	8	0	1	1
1	8	1 <sup>1</sup>	0	1

NOTES:

1. The address bit identifies the frame as an address character. See section on Receiver Wakeup



## 4.5 Baud Rate Generation

A 13-bit modulus counter in the baud rate generator derives the baud rate for both the receiver and the transmitter. The value from 0 to 8191 written to the SBR12–SBR0 bits determines the bus clock divisor. The SBR bits are in the SCI baud rate registers (SCIBDH and SCIBDL). The baud rate clock is synchronized with the bus clock and drives the receiver. The baud rate clock divided by 16 drives the transmitter. The receiver has an acquisition rate of 16 samples per bit time.

Baud rate generation is subject to one source of error:

- Integer division of the bus clock may not give the exact target frequency.

**Table 4-3** lists some examples of achieving target baud rates with a bus clock frequency of 25 MHz.

When IREN=0 then,

SCI baud rate = SCI bus clock / (16 \* SCIBR[12:0])

**Table 4-3 Baud Rates (Example: Bus Clock = 25 Mhz)**

Bits SBR[12:0]	Receiver Clock (Hz)	Transmitter Clock (Hz)	Target Baud Rate	Error (%)
41	609,756.1	38,109.8	38,400	.76
81	308,642.0	19,290.1	19,200	.47
163	153,374.2	9585.9	9,600	.16
326	76,687.1	4792.9	4,800	.15
651	38,402.5	2400.2	2,400	.01
1302	19,201.2	1200.1	1,200	.01
2604	9600.6	600.0	600	.00
5208	4800.0	300.0	300	.00
10417	2400.0	150.0	150	.00
14204	1760.1	110.0	110	.00

## 4.6 Transmitter

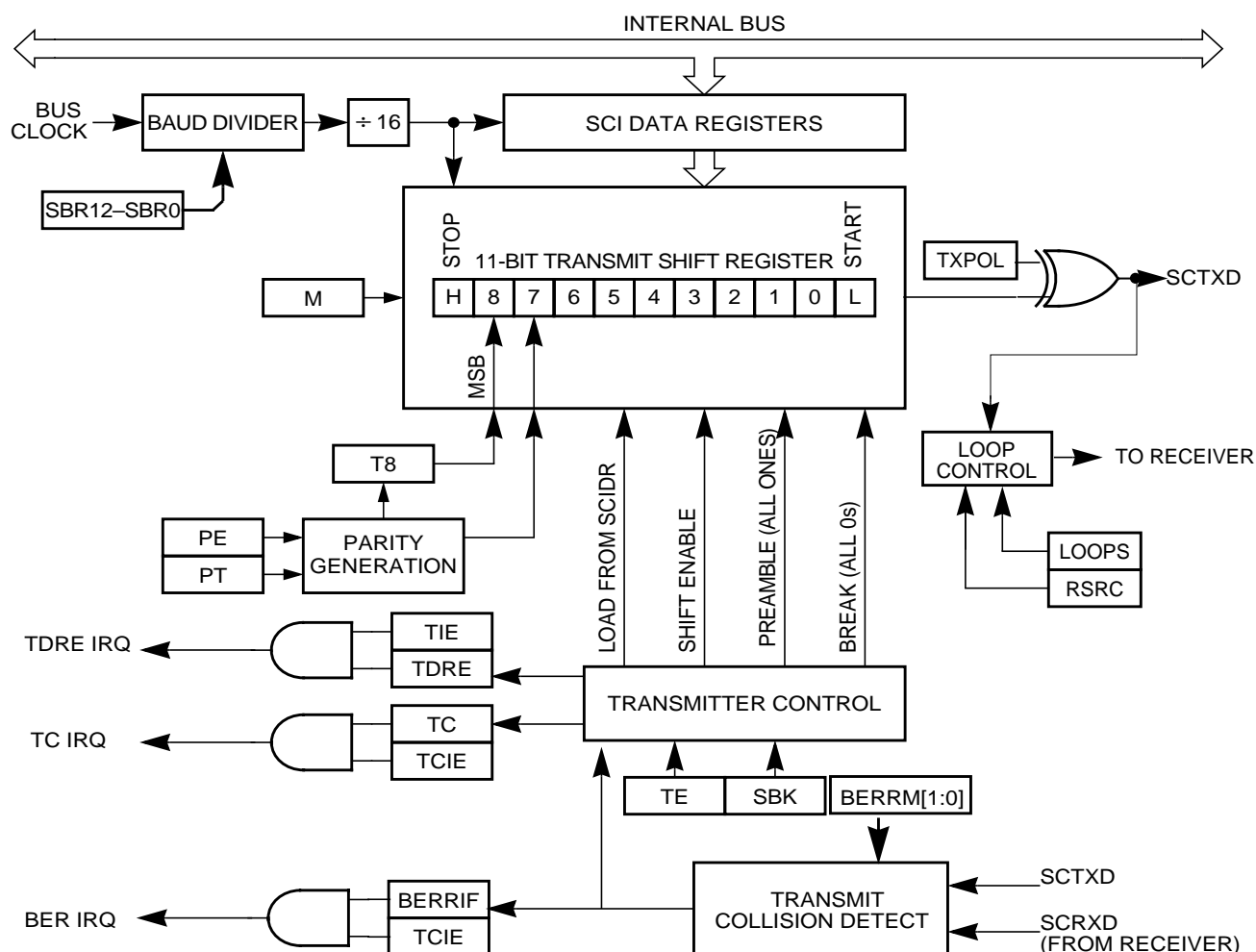


Figure 4-3 Transmitter Block Diagram

### 4.6.1 Transmitter Character Length

The SCI transmitter can accommodate either 8-bit or 9-bit data characters. The state of the **M** bit in SCI control register 1 (**SCICR1**) determines the length of data characters. When transmitting 9-bit data, bit **T8** in SCI data register high (**SCIDRH**) is the ninth bit (bit 8).

### 4.6.2 Character Transmission

To transmit data, the MCU writes the data bits to the SCI data registers (**SCIDRH/SCIDRL**), which in turn are transferred to the transmitter shift register. The transmit shift register then shifts a frame out through the **TXD** pin, after it has prefaced them with a start bit and appended them with a stop bit. The SCI data

registers (SCIDRH and SCIDRL) are the write-only buffers between the internal data bus and the transmit shift register.

The SCI also sets a flag, the transmit data register empty flag (TDRE), every time it transfers data from the buffer (SCIDRH/L) to the transmitter shift register. The transmit driver routine may respond to this flag by writing another byte to the Transmitter buffer (SCIDRH/SCIDRL), while the shift register is still shifting out the first byte.

To initiate an SCI transmission:

1. Configure the SCI:
  - a. Select a baud rate. Write this value to the SCI baud registers (SCIBDH/L) to begin the baud rate generator. Remember that the baud rate generator is disabled when the baud rate is zero. Writing to the SCIBDH has no effect without also writing to SCIBDL.
  - b. Write to SCICR1 to configure word length, parity, and other configuration bits (LOOPS,RSRC,M,WAKE,ILT,PE,PT).
  - c. Enable the transmitter, interrupts, receive, and wake up as required, by writing to the SCICR2 register bits (TIE,TCIE,RIE,ILIE,TE,RE,RWU,SBK). A preamble or idle character will now be shifted out of the transmitter shift register.
2. Transmit Procedure for Each Byte:
  - a. Poll the TDRE flag by reading the SCISR1 or responding to the TDRE interrupt. Keep in mind that the TDRE bit resets to one.
  - b. If the TDRE flag is set, write the data to be transmitted to SCIDRH/L, where the ninth bit is written to the T8 bit in SCIDRH if the SCI is in 9-bit data format. A new transmission will not result until the TDRE flag has been cleared.
3. Repeat step 2 for each subsequent transmission.

**NOTE:** *The TDRE flag is set when the shift register is loaded with the next data to be transmitted from SCIDRH/L, which happens, generally speaking, a little over half-way through the stop bit of the previous frame. Specifically, this transfer occurs 9/16ths of a bit time AFTER the start of the stop bit of the previous frame.*

Writing the TE bit from 0 to a 1 automatically loads the transmit shift register with a preamble of 10 logic 1s (if M = 0) or 11 logic 1s (if M = 1). After the preamble shifts out, control logic transfers the data from the SCI data register into the transmit shift register. A logic 0 start bit automatically goes into the least significant bit position of the transmit shift register. A logic 1 stop bit goes into the most significant bit position.

Hardware supports odd or even parity. When parity is enabled, the most significant bit (msb) of the data character is the parity bit.

The transmit data register empty flag, TDRE, in SCI status register 1 (SCISR1) becomes set when the SCI data register transfers a byte to the transmit shift register. The TDRE flag indicates that the SCI data register can accept new data from the internal data bus. If the transmit interrupt enable bit, TIE, in SCI control register 2 (SCICR2) is also set, the TDRE flag generates a transmitter interrupt request.

When the transmit shift register is not transmitting a frame, the TXD pin goes to the idle condition, logic 1. If at any time software clears the TE bit in SCI control register 2 (SCICR2), the transmitter enable signal goes low and the transmit signal goes idle.

If software clears TE while a transmission is in progress (TC = 0), the frame in the transmit shift register continues to shift out. To avoid accidentally cutting off the last frame in a message, always wait for TDRE to go high after the last frame before clearing TE.

To separate messages with preambles with minimum idle line time, use this sequence between messages:

1. Write the last byte of the first message to SCIDRH/L.
2. Wait for the TDRE flag to go high, indicating the transfer of the last frame to the transmit shift register.
3. Queue a preamble by clearing and then setting the TE bit.
4. Write the first byte of the second message to SCIDRH/L.

### 4.6.3 Break Characters

Writing a logic 1 to the send break bit, SBK, in SCI control register 2 (SCICR2) loads the transmit shift register with a break character. A break character contains all logic 0s and has no start, stop, or parity bit. Break character length depends on the M bit in SCI control register 1 (SCICR1). As long as SBK is at logic 1, transmitter logic continuously loads break characters into the transmit shift register. After software clears the SBK bit, the shift register finishes transmitting the last break character and then transmits at least one logic 1. The automatic logic 1 at the end of a break character guarantees the recognition of the start bit of the next frame.

The SCI recognizes a break character when there are 10 or 11 (M=0 or M=1) consecutive zero received. Depending if the break detect feature is enabled or not receiving a break character has these effects on SCI registers.

If the break detect feature is disabled (BKDFE = 0):

- Sets the framing error flag, FE
- Sets the receive data register full flag, RDRF
- Clears the SCI data registers (SCIDRH/L)
- May set the overrun flag, OR, noise flag, NF, parity error flag, PE, or the receiver active flag, RAF (see 3.4.4 and 3.4.5 SCI Status Register 1 and 2)

If the break detect feature is enabled (BKDFE = 1) there are two scenarios<sup>1</sup>

The break is detected right from a start bit or is detected during a byte reception.

- Sets the break detect interrupt flag, BLDIF
- Does not change the data register full flag, RDRF or overrun flag OR

#### NOTES:

1. A Break character in this context are either 10 or 11 consecutive zero received bits

- Does not change the framing error flag FE, parity error flag PE.
- Does not clear the SCI data registers (SCIDRH/L)
- May set noise flag NF, or receiver active flag RAF.

Figure 4-4 shows two cases of break detect. In trace RXD\_1 the break symbol starts with the start bit, while in RXD\_2 the break starts in the middle of a transmission. If BRKDFE = 1, in RXD\_1 case there will be no byte transferred to the receive buffer and the RDRF flag will not be modified. Also no framing error or parity error will be flagged from this transfer. In RXD\_2 case, however the break signal starts later during the transmission. At the expected stop bit position the byte received so far will be transferred to the receive buffer, the receive data register full flag will be set, a framing error and if enabled and appropriate a parity error will be set. Once the break is detected the BRKDIF flag will be set.

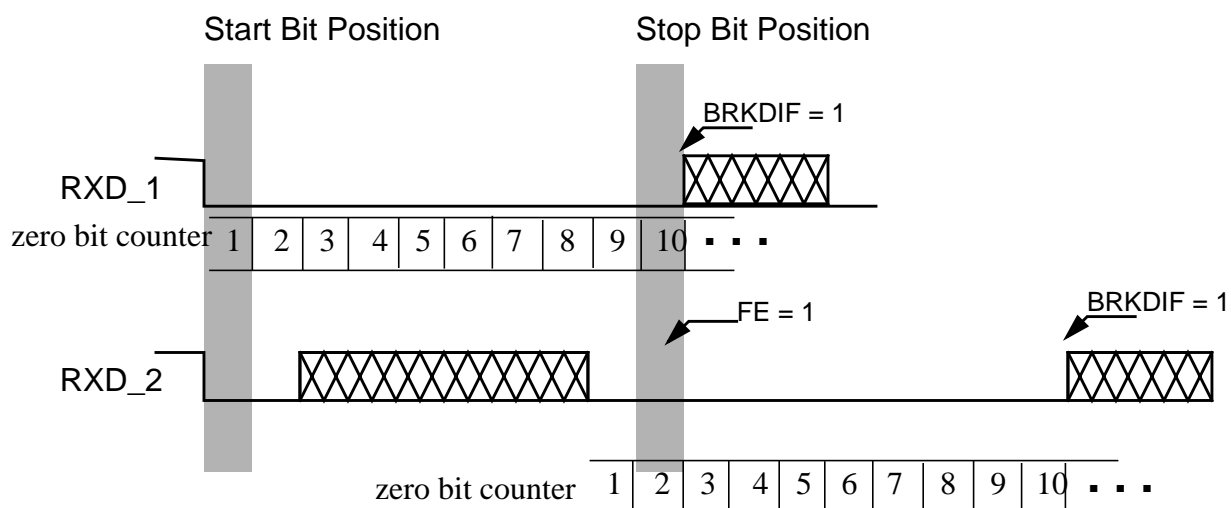


Figure 4-4 Break Detection if BRKDFE = 1(M=0)

#### 4.6.4 Idle Characters

An idle character (or preamble) contains all logic 1s and has no start, stop, or parity bit. Idle character length depends on the M bit in SCI control register 1 (SCICR1). The preamble is a synchronizing idle character that begins the first transmission initiated after writing the TE bit from 0 to 1.

If the TE bit is cleared during a transmission, the TXD pin becomes idle after completion of the transmission in progress. Clearing and then setting the TE bit during a transmission queues an idle character to be sent after the frame currently being transmitted.

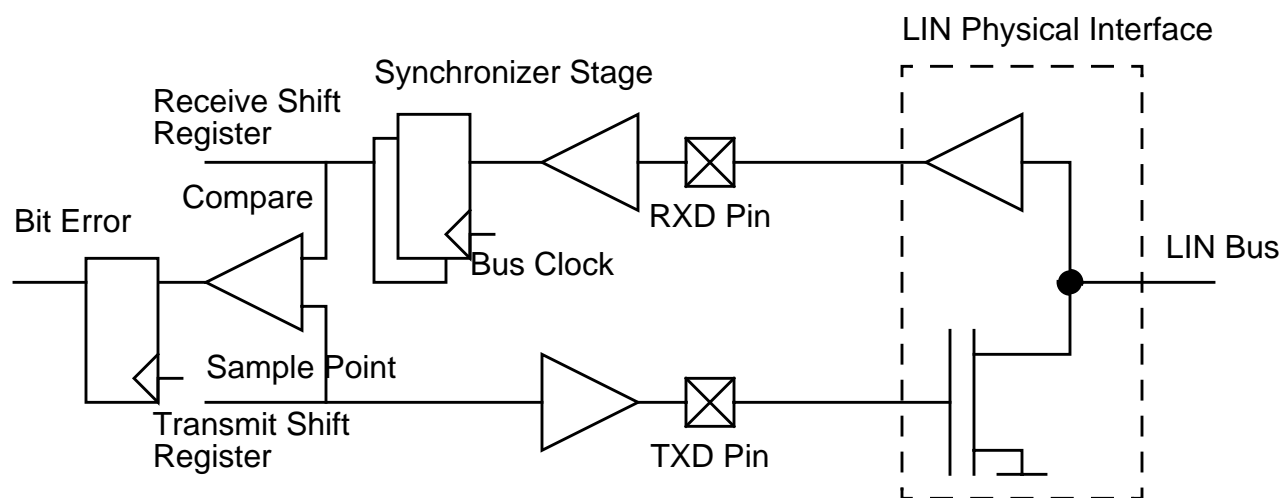
**NOTE:** When queueing an idle character, return the TE bit to logic 1 before the stop bit of the current frame shifts out through the TXD pin. Setting TE after the stop bit appears on TXD causes data previously written to the SCI data register to be lost.

*Toggle the TE bit for a queued idle character while the TDRE flag is set and immediately before writing the next byte to the SCI data register.*

**NOTE:** *If the TE bit is clear and the transmission is complete, the SCI is not the master of the TXD pin*

## 4.6.5 LIN Transmit Collision Detection

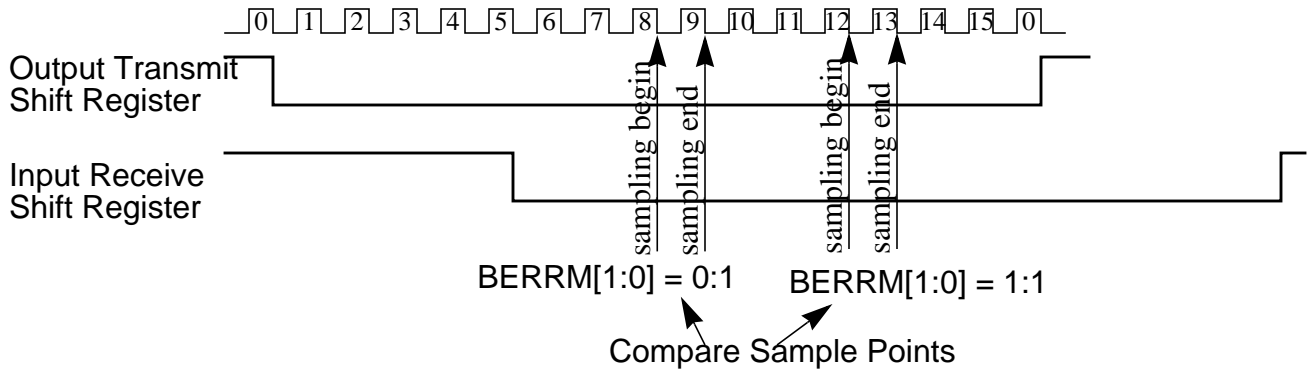
This module allows to check for collisions on the LIN bus.



**Figure 4-5 Collision Detect Principle**

If the bit error circuit is enabled ( $BERRM[1:0] = 0:1$  or  $= 1:0$ ) the error detect circuit will compare the transmitted and the received data stream at a point in time and flag any mismatch. The timing checks run when transmitter is active (not idle). As soon as a mismatch between the transmitted data and the received data is detected the following happens:

- The next bit transmitted will have a high level ( $TXPOL = 0$ ) or low level ( $TXPOL = 1$ )
- The transmission is aborted and the byte in transmit buffer is discarded.
- the transmit data register empty and the transmission complete flag will be set
- The bit error interrupt flag, BERRIF, will be set.
- No further transmissions will take place until the BERRIF is cleared.



**Figure 4-6 Timing Diagram Bit Error Detection**

if the bit error detect feature is disabled, the bit error interrupt flag is cleared.

*NOTE: The RXPOL and TXPOL bit should be set the same when transmission collision detect feature is enabled, otherwise the bit error interrupt flag may be set incorrectly.*

## 4.7 Receiver

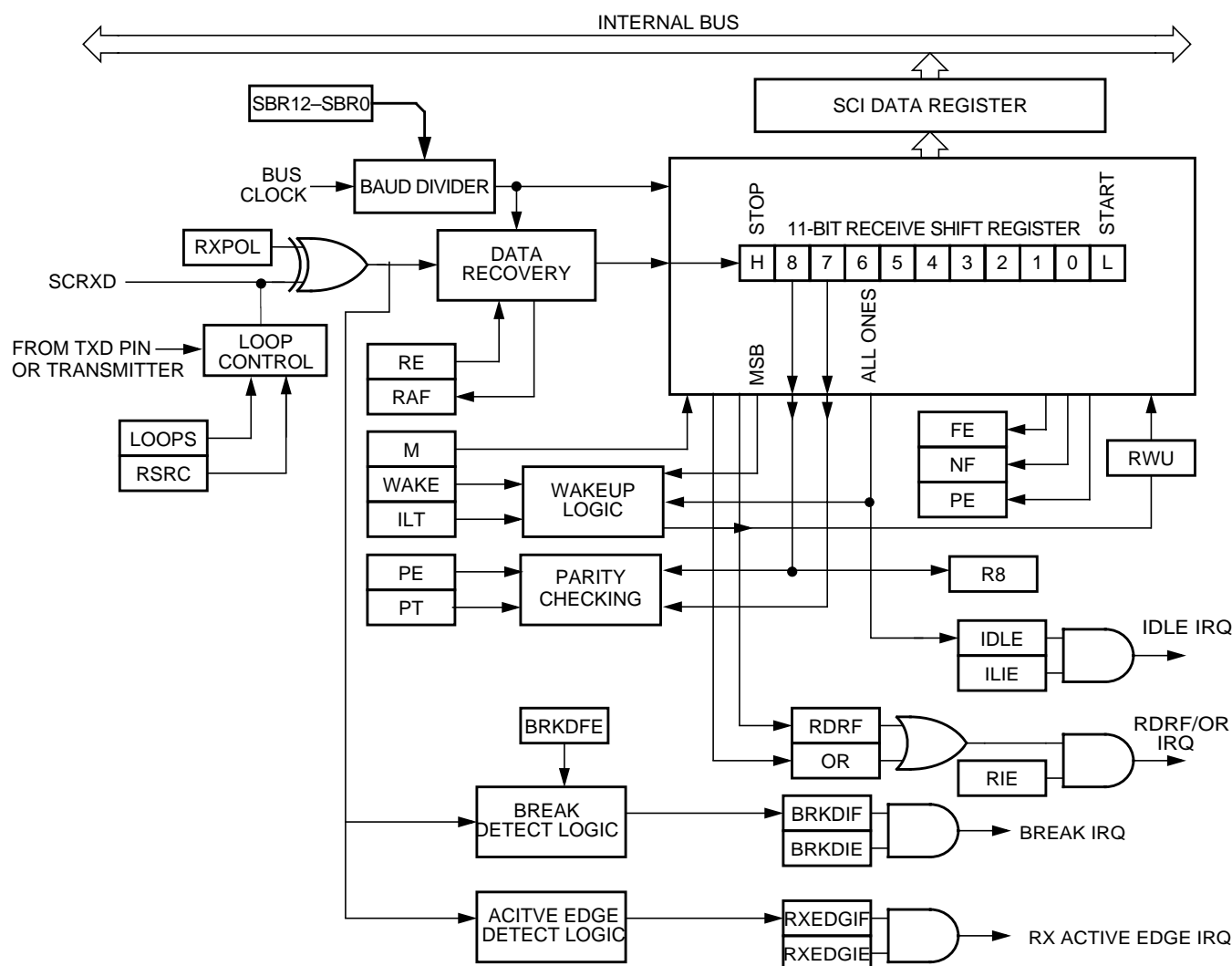


Figure 4-7 SCI Receiver Block Diagram

### 4.7.1 Receiver Character Length

The SCI receiver can accommodate either 8-bit or 9-bit data characters. The state of the M bit in SCI control register 1 (SCICR1) determines the length of data characters. When receiving 9-bit data, bit R8 in SCI data register high (SCIDRH) is the ninth bit (bit 8).

### 4.7.2 Character Reception

During an SCI reception, the receive shift register shifts a frame in from the RXD pin. The SCI data register is the read-only buffer between the internal data bus and the receive shift register.



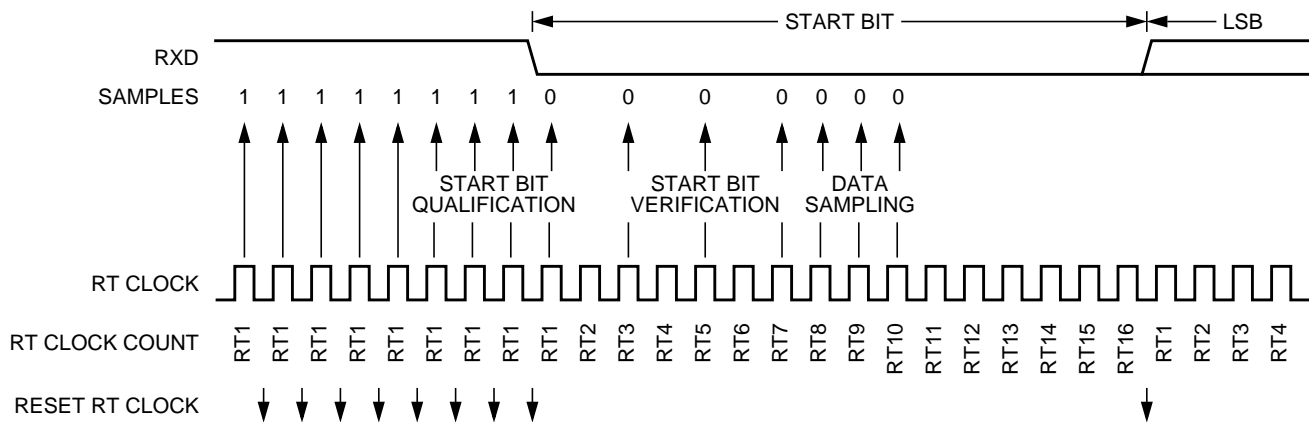
After a complete frame shifts into the receive shift register, the data portion of the frame transfers to the SCI data register. The receive data register full flag, RDRF, in SCI status register 1 (SCISR1) becomes set, indicating that the received byte can be read. If the receive interrupt enable bit, RIE, in SCI control register 2 (SCICR2) is also set, the RDRF flag generates an RDRF interrupt request.

### 4.7.3 Data Sampling

The RT clock rate. The RT clock is an internal signal with a frequency 16 times the baud rate. To adjust for baud rate mismatch, the RT clock (see **Figure 4-8**) is re-synchronized:

- After every start bit
- After the receiver detects a data bit change from logic 1 to logic 0 (after the majority of data bit samples at RT8, RT9, and RT10 returns a valid logic 1 and the majority of the next RT8, RT9, and RT10 samples returns a valid logic 0)

To locate the start bit, data recovery logic does an asynchronous search for a logic 0 preceded by three logic 1s. When the falling edge of a possible start bit occurs, the RT clock begins to count to 16.



**Figure 4-8 Receiver Data Sampling**

To verify the start bit and to detect noise, data recovery logic takes samples at RT3, RT5, and RT7. **Table 4-4** summarizes the results of the start bit verification samples.

**Table 4-4 Start Bit Verification**

RT3, RT5, and RT7 Samples	Start Bit Verification	Noise Flag
000	Yes	0
001	Yes	1
010	Yes	1
011	No	0
100	Yes	1
101	No	0

RT3, RT5, and RT7 Samples	Start Bit Verification	Noise Flag
110	No	0
111	No	0

If start bit verification is not successful, the RT clock is reset and a new search for a start bit begins.

To determine the value of a data bit and to detect noise, recovery logic takes samples at RT8, RT9, and RT10. **Table 4-5** summarizes the results of the data bit samples.

**Table 4-5 Data Bit Recovery**

RT8, RT9, and RT10 Samples	Data Bit Determination	Noise Flag
000	0	0
001	0	1
010	0	1
011	1	1
100	0	1
101	1	1
110	1	1
111	1	0

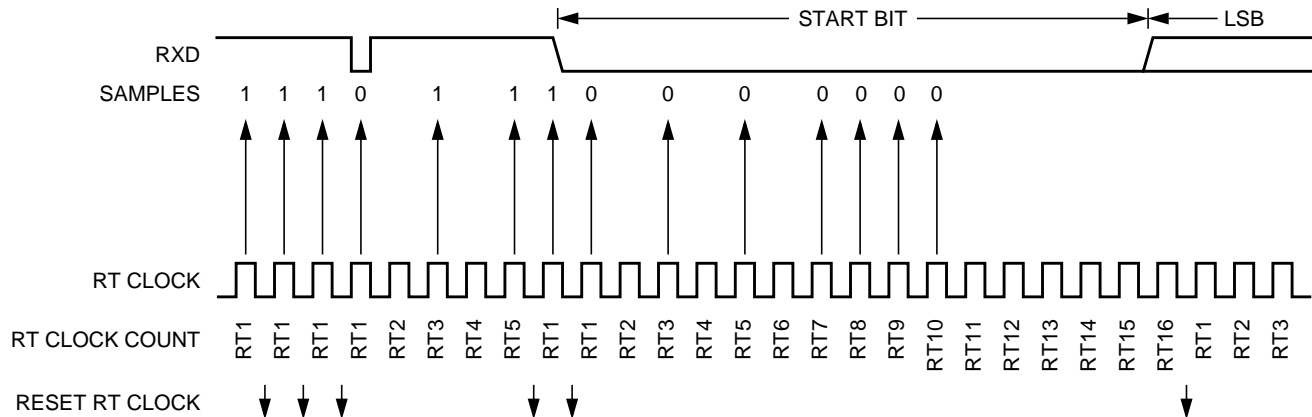
**NOTE:** The RT8, RT9, and RT10 samples do not affect start bit verification. If any or all of the RT8, RT9, and RT10 start bit samples are logic 1s following a successful start bit verification, the noise flag (NF) is set and the receiver assumes that the bit is a start bit (logic 0).

To verify a stop bit and to detect noise, recovery logic takes samples at RT8, RT9, and RT10. **Table 4-6** summarizes the results of the stop bit samples.

**Table 4-6 Stop Bit Recovery**

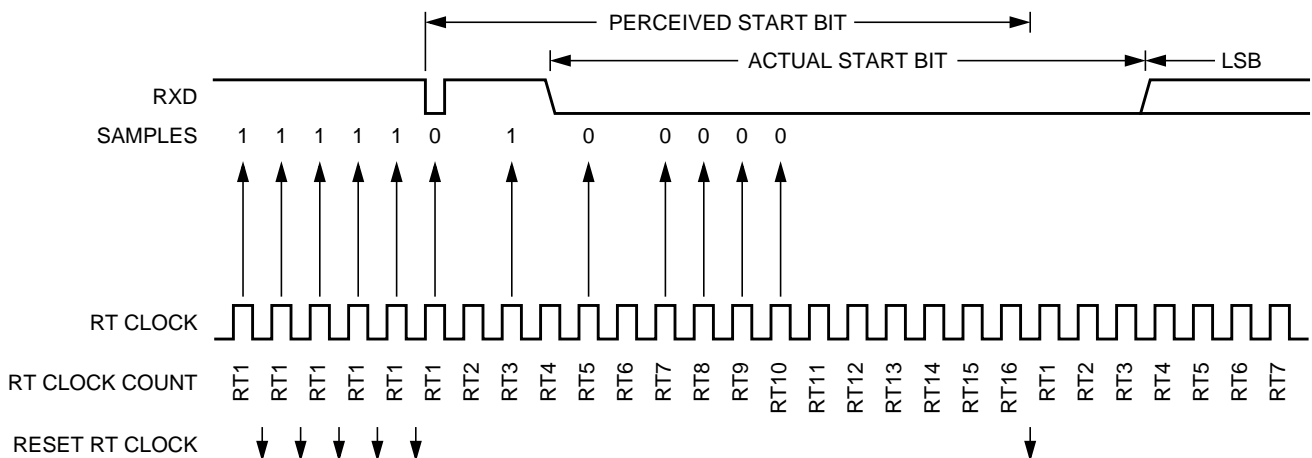
RT8, RT9, and RT10 Samples	Framing Error Flag	Noise Flag
000	1	0
001	1	1
010	1	1
011	0	1
100	1	1
101	0	1
110	0	1
111	0	0

In **Figure 4-9** the verification samples RT3 and RT5 determine that the first low detected was noise and not the beginning of a start bit. The RT clock is reset and the start bit search begins again. The noise flag is not set because the noise occurred before the start bit was found.



**Figure 4-9 Start Bit Search Example 1**

In **Figure 4-10**, verification sample at RT3 is high. The RT3 sample sets the noise flag. Although the perceived bit time is misaligned, the data samples RT8, RT9, and RT10 are within the bit time and data recovery is successful.



**Figure 4-10 Start Bit Search Example 2**

In **Figure 4-11**, a large burst of noise is perceived as the beginning of a start bit, although the test sample at RT5 is high. The RT5 sample sets the noise flag. Although this is a worst-case misalignment of

perceived bit time, the data samples RT8, RT9, and RT10 are within the bit time and data recovery is successful.

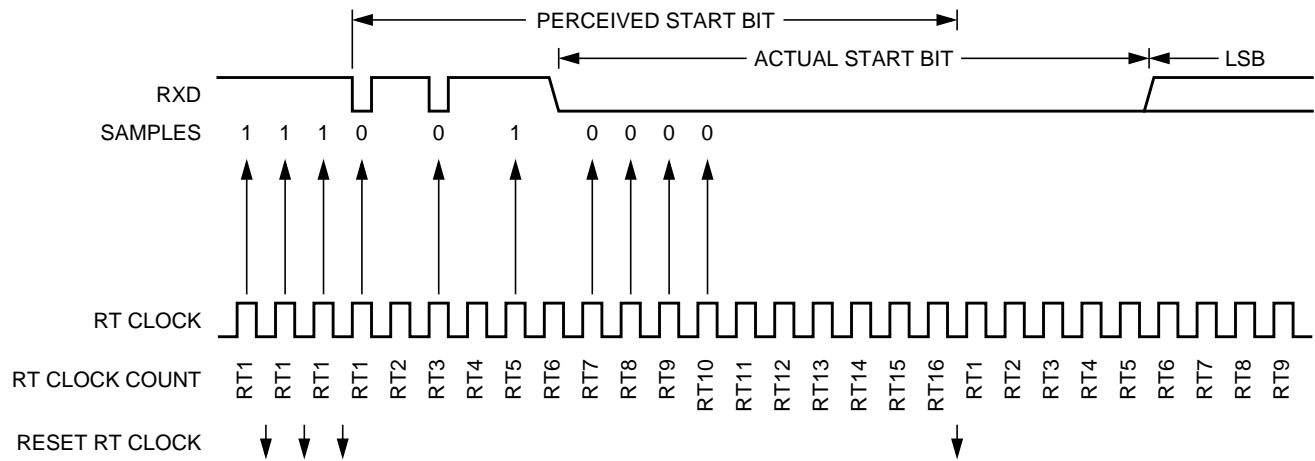


Figure 4-11 Start Bit Search Example 3

Figure 4-12 shows the effect of noise early in the start bit time. Although this noise does not affect proper synchronization with the start bit time, it does set the noise flag.

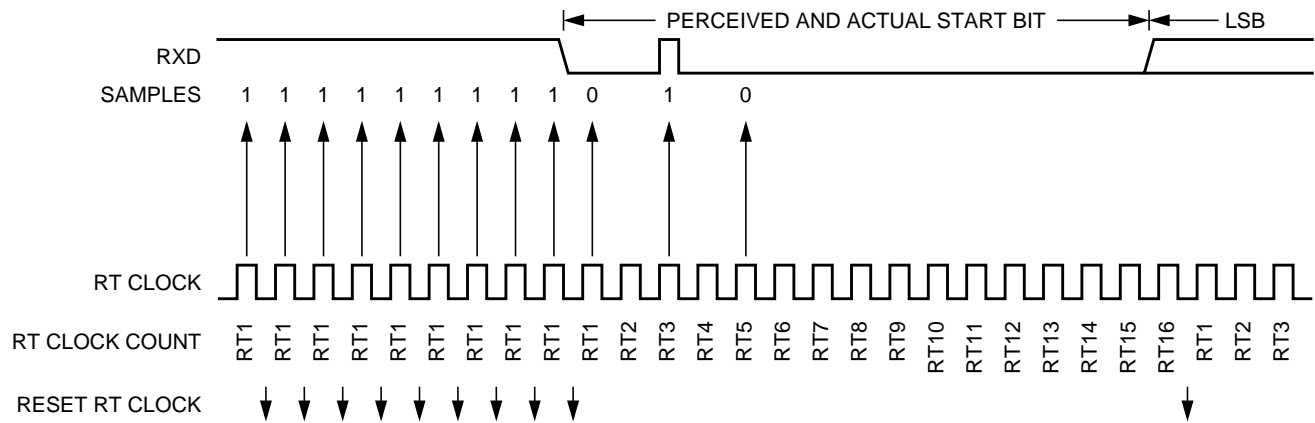
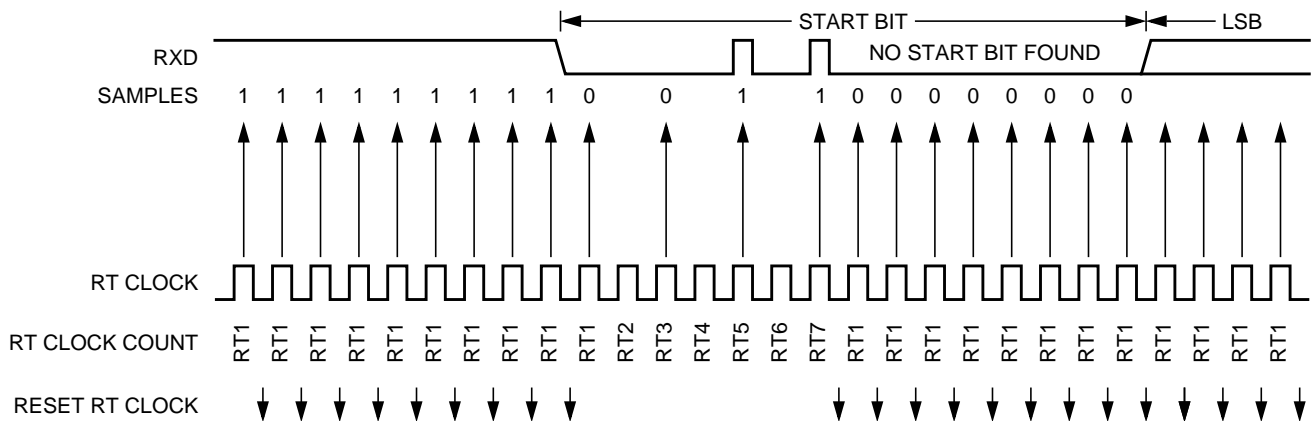


Figure 4-12 Start Bit Search Example 4

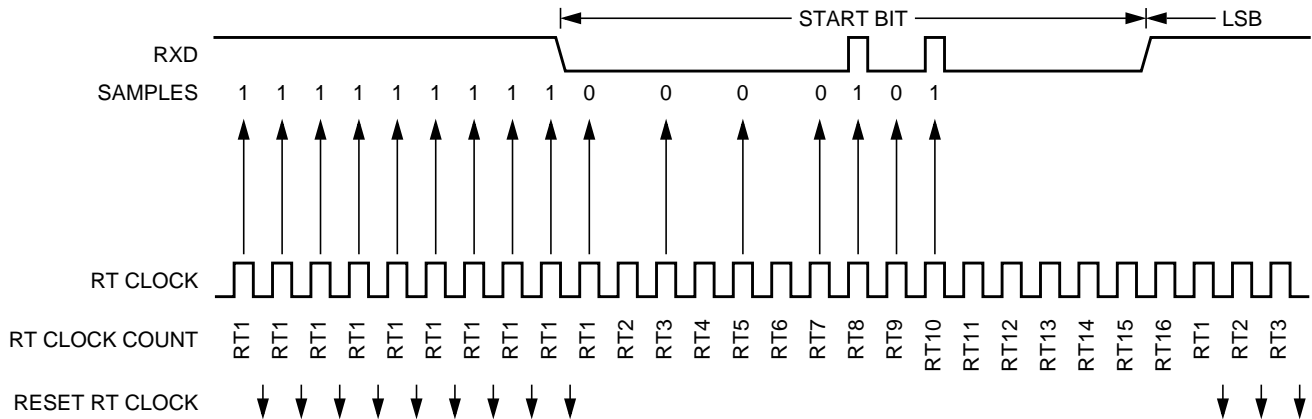
Figure 4-13 shows a burst of noise near the beginning of the start bit that resets the RT clock. The sample after the reset is low but is not preceded by three high samples that would qualify as a falling edge.

Depending on the timing of the start bit search and on the data, the frame may be missed entirely or it may set the framing error flag.



**Figure 4-13 Start Bit Search Example 5**

In **Figure 4-14**, a noise burst makes the majority of data samples RT8, RT9, and RT10 high. This sets the noise flag but does not reset the RT clock. In start bits only, the RT8, RT9, and RT10 data samples are ignored.



**Figure 4-14 Start Bit Search Example 6**

#### 4.7.4 Framing Errors

If the data recovery logic does not detect a logic 1 where the stop bit should be in an incoming frame, it sets the framing error flag, FE, in SCI status register 1 (SCISR1). A break character also sets the FE flag because a break character has no stop bit. The FE flag is set at the same time that the RDRF flag is set.

#### 4.7.5 Baud Rate Tolerance

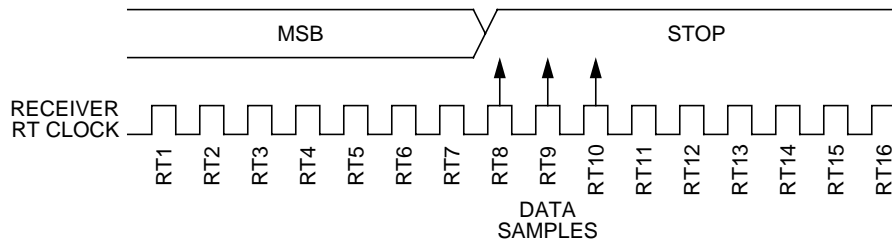
A transmitting device may be operating at a baud rate below or above the receiver baud rate. Accumulated bit time misalignment can cause one of the three stop bit data samples (RT8, RT9, and RT10) to fall

outside the actual stop bit. A noise error will occur if the RT8, RT9, and RT10 samples are not all the same logical values. A framing error will occur if the receiver clock is misaligned in such a way that the majority of the RT8, RT9, and RT10 stop bit samples are a logic zero.

As the receiver samples an incoming frame, it re-synchronizes the RT clock on any valid falling edge within the frame. Re synchronization within frames will correct a misalignment between transmitter bit times and receiver bit times.

#### 4.7.5.1 Slow Data Tolerance

**Figure 4-15** shows how much a slow received frame can be misaligned without causing a noise error or a framing error. The slow stop bit begins at RT8 instead of RT1 but arrives in time for the stop bit data samples at RT8, RT9, and RT10.



**Figure 4-15 Slow Data**

Let's take RTr as receiver RT clock and RTt as transmitter RT clock.

For an 8-bit data character, it takes the receiver 9 bit times x 16 RTr cycles + 7 RTr cycles = 151 RTr cycles to start data sampling of the stop bit.

With the misaligned character shown in **Figure 4-15**, the receiver counts 151 RTr cycles at the point when the count of the transmitting device is 9 bit times x 16 RTt cycles = 144 RTt cycles.

The maximum percent difference between the receiver count and the transmitter count of a slow 8-bit data character with no errors is:

$$((151 - 144) / 151) \times 100 = 4.63\%$$

For a 9-bit data character, it takes the receiver 10 bit times x 16 RTr cycles + 7 RTr cycles = 167 RTr cycles to start data sampling of the stop bit.

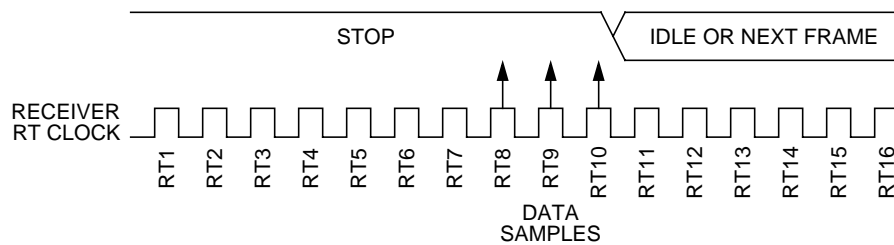
With the misaligned character shown in **Figure 4-15**, the receiver counts 167 RTr cycles at the point when the count of the transmitting device is 10 bit times x 16 RTt cycles = 160 RTt cycles.

The maximum percent difference between the receiver count and the transmitter count of a slow 9-bit character with no errors is:

$$((167 - 160) / 167) \times 100 = 4.19\%$$

### 4.7.5.2 Fast Data Tolerance

**Figure 4-16** shows how much a fast received frame can be misaligned. The fast stop bit ends at RT10 instead of RT16 but is still sampled at RT8, RT9, and RT10.



**Figure 4-16 Fast Data**

For an 8-bit data character, it takes the receiver 9 bit times x 16 RTr cycles + 10 RTr cycles = 154 RTr cycles to finish data sampling of the stop bit.

With the misaligned character shown in **Figure 4-16**, the receiver counts 154 RTr cycles at the point when the count of the transmitting device is 10 bit times x 16 RTt cycles = 160 RTt cycles.

The maximum percent difference between the receiver count and the transmitter count of a fast 8-bit character with no errors is:

$$((160 - 154) / 160) \times 100 = 3.75\%$$

For a 9-bit data character, it takes the receiver 10 bit times x 16 RTr cycles + 10 RTr cycles = 170 RTr cycles to finish data sampling of the stop bit.

With the misaligned character shown in **Figure 4-16**, the receiver counts 170 RTr cycles at the point when the count of the transmitting device is 11 bit times x 16 RTt cycles = 176 RTt cycles.

The maximum percent difference between the receiver count and the transmitter count of a fast 9-bit character with no errors is:

$$((176 - 170) / 176) \times 100 = 3.40\%$$

### 4.7.6 Receiver Wakeup

To enable the SCI to ignore transmissions intended only for other receivers in multiple-receiver systems, the receiver can be put into a standby state. Setting the receiver wakeup bit, RWU, in SCI control register 2 (SCICR2) puts the receiver into standby state during which receiver interrupts are disabled. The SCI will still load the receive data into the SCIDRH/L registers, but it will not set the RDRF flag.

The transmitting device can address messages to selected receivers by including addressing information in the initial frame or frames of each message.

The WAKE bit in SCI control register 1 (SCICR1) determines how the SCI is brought out of the standby state to process an incoming message. The WAKE bit enables either idle line wakeup or address mark wakeup.

#### 4.7.6.1 Idle input line wakeup (WAKE = 0)

In this wakeup method, an idle condition on the RXD pin clears the RWU bit and wakes up the SCI. The initial frame or frames of every message contain addressing information. All receivers evaluate the addressing information, and receivers for which the message is addressed process the frames that follow. Any receiver for which a message is not addressed can set its RWU bit and return to the standby state. The RWU bit remains set and the receiver remains on standby until another idle character appears on the RXD pin.

Idle line wakeup requires that messages be separated by at least one idle character and that no message contains idle characters.

The idle character that wakes a receiver does not set the receiver idle bit, IDLE, or the receive data register full flag, RDRF.

The idle line type bit, ILT, determines whether the receiver begins counting logic 1s as idle character bits after the start bit or after the stop bit. ILT is in SCI control register 1 (SCICR1).

#### 4.7.6.2 Address mark wakeup (WAKE = 1)

In this wakeup method, a logic 1 in the most significant bit (msb) position of a frame clears the RWU bit and wakes up the SCI. The logic 1 in the msb position marks a frame as an address frame that contains addressing information. All receivers evaluate the addressing information, and the receivers for which the message is addressed process the frames that follow. Any receiver for which a message is not addressed can set its RWU bit and return to the standby state. The RWU bit remains set and the receiver remains on standby until another address frame appears on the RXD pin.

The logic 1 msb of an address frame clears the receiver's RWU bit before the stop bit is received and sets the RDRF flag.

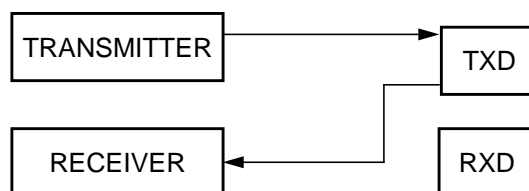
Address mark wakeup allows messages to contain idle characters but requires that the msb be reserved for use in address frames.

**NOTE:** *With the WAKE bit clear, setting the RWU bit after the RXD pin has been idle can cause the receiver to wake up immediately.*

### 4.8 Single-Wire Operation

Normally, the SCI uses two pins for transmitting and receiving. In single-wire operation, the RXD pin is disconnected from the SCI. The SCI uses the TXD pin for both receiving and transmitting.





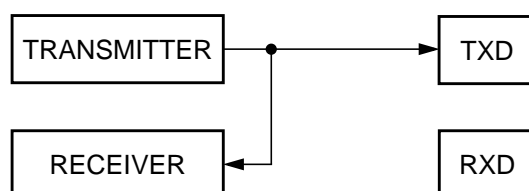
**Figure 4-17 Single-Wire Operation (LOOPS = 1, RSRC = 1)**

Enable single-wire operation by setting the LOOPS bit and the receiver source bit, RSRC, in SCI control register 1 (SCICR1). Setting the LOOPS bit disables the path from the RXD pin to the receiver. Setting the RSRC bit connects the TXD pin to the receiver. Both the transmitter and receiver must be enabled (TE=1 and RE=1). The TXDIR bit (SCISR2[1]) determines whether the TXD pin is going to be used as an input (TXDIR = 0) or an output (TXDIR = 1) in this mode of operation.

**NOTE:** In single-wire operation data from the TXD pin is inverted if RXPOL is set.

## 4.9 Loop Operation

In loop operation the transmitter output goes to the receiver input. The RXD pin is disconnected from the SCI



**Figure 4-18 Loop Operation (LOOPS = 1, RSRC = 0)**

Enable loop operation by setting the LOOPS bit and clearing the RSRC bit in SCI control register 1 (SCICR1). Setting the LOOPS bit disables the path from the RXD pin to the receiver. Clearing the RSRC bit connects the transmitter output to the receiver input. Both the transmitter and receiver must be enabled (TE = 1 and RE = 1).

**NOTE:** In loop operation data from the transmitter is not recognized by the receiver if RXPOL and TXPOL are not the same.

## Section 5 Initialization/Application Information

### 5.1 Reset Initialization

See **Section 3.3** Register Descriptions.

### 5.2 Modes of Operation

#### 5.2.1 Run Mode

Normal mode of operation.

To initialize a SCI transmission, See **4.6.2** Character Transmission;

#### 5.2.2 Wait Mode

SCI operation in wait mode depends on the state of the SCISWAI bit in the SCI control register 1 (SCICR1).

- If SCISWAI is clear, the SCI operates normally when the CPU is in wait mode.
- If SCISWAI is set, SCI clock generation ceases and the SCI module enters a power-conservation state when the CPU is in wait mode. Setting SCISWAI does not affect the state of the receiver enable bit, RE, or the transmitter enable bit, TE.

If SCISWAI is set, any transmission or reception in progress stops at wait mode entry. The transmission or reception resumes when either an internal or external interrupt brings the CPU out of wait mode. Exiting wait mode by reset aborts any transmission or reception in progress and resets the SCI.

#### 5.2.3 Stop Mode

The SCI is inactive during stop mode for reduced power consumption. The STOP instruction does not affect the SCI register states, but the SCI bus clock will be disabled. The SCI operation resumes from where it left off after an external interrupt brings the CPU out of stop mode. Exiting stop mode by reset aborts any transmission or reception in progress and resets the SCI.

The receive input active edge detect circuit is still active in stop mode. An active edge on the receive input can be used to bring the CPU out of stop mode.

### 5.3 Interrupt Operation

#### 5.3.1 General

This section describes the interrupt originated by the SCI block. The MCU must service the interrupt requests. **Table 5-1** lists the eight interrupt sources of the SCI.

**Table 5-1 SCI Interrupt Sources**

Interrupt	Source	Local Enable	Description
TDRE	SCISR1[7]	TIE	Active high level. Indicates that a byte was transferred from SCIDRH/L to the transmit shift register.
TC	SCISR1[6]	TCIE	Active high level. Indicates that a transmit is complete.
RDRF	SCISR1[5]	RIE	Active high level. The RDRF interrupt indicates that received data is available in the SCI data register.
OR	SCISR1[3]		Active high level. This interrupt indicates that an overrun condition has occurred.
IDLE	SCISR1[4]	ILIE	Active high level. Indicates that receiver input has become idle.
RXEDGIF	SCIASR1[7]	RXEDGIE	Active high level. Indicates that an active edge (falling for RXPOL = 0, rising for RXPOL = 1) was detected.
BERRIF	SCIASR1[1]	BERRIE	Active high level. Indicates that a mismatch between transmitted and received data in a single wire application has happened.
BKDIF	SCIASR1[0]	BRKDIE	Active high level. Indicates that a break character has been received.

### 5.3.2 Description of Interrupt Operation

The SCI only originates interrupt requests. The following is a description of how the SCI makes a request and how the MCU should acknowledge that request. The interrupt vector offset and interrupt number are chip dependent. The SCI only has a single interrupt line (**SCI Interrupt Signal**, active high operation) and all the following interrupts, when generated, are ORed together and issued through that port.

#### 5.3.2.1 TDRE Description

The TDRE interrupt is set high by the SCI when the transmit shift register receives a byte from the SCI data register. A TDRE interrupt indicates that the transmit data register (SCIDRH/L) is empty and that a new byte can be written to the SCIDRH/L for transmission. Clear TDRE by reading SCI status register 1 with TDRE set and then writing to SCI data register low (SCIDRL).

#### 5.3.2.2 TC Description

The TC interrupt is set by the SCI when a transmission has been completed. Transmission is completed when all bits including the stop bit (if transmitted) have been shifted out and no data is queued to be transmitted. No stop bit is transmitted when sending a break character and the TC flag is set (providing there is no more data queued for transmission) when the break character has been shifted out. A TC interrupt indicates that there is no transmission in progress. TC is set high when the TDRE flag is set and no data, preamble, or break character is being transmitted. When TC is set, the TXD pin becomes idle (logic 1). Clear TC by reading SCI status register 1 (SCISR1) with TC set and then writing to SCI data

register low (SCIDRL).TC is cleared automatically when data, preamble, or break is queued and ready to be sent.

### **5.3.2.3 RDRF Description**

The RDRF interrupt is set when the data in the receive shift register transfers to the SCI data register. A RDRF interrupt indicates that the received data has been transferred to the SCI data register and that the byte can now be read by the MCU. The RDRF interrupt is cleared by reading the SCI status register one (SCISR1) and then reading SCI data register low (SCIDRL).

### **5.3.2.4 OR Description**

The OR interrupt is set when software fails to read the SCI data register before the receive shift register receives the next frame. The newly acquired data in the shift register will be lost in this case, but the data already in the SCI data registers is not affected. The OR interrupt is cleared by reading the SCI status register one (SCISR1) and then reading SCI data register low (SCIDRL).

### **5.3.2.5 IDLE Description**

The IDLE interrupt is set when 10 consecutive logic 1s (if M=0) or 11 consecutive logic 1s (if M=1) appear on the receiver input. Once the IDLE is cleared, a valid frame must again set the RDRF flag before an idle condition can set the IDLE flag. Clear IDLE by reading SCI status register 1 (SCISR1) with IDLE set and then reading SCI data register low (SCIDRL).

### **5.3.2.6 RXEDGIF Description**

The RXEDGIF interrupt is set when an active edge (falling if RXPOL =0, rising if RXPOL = 1) on the RXD pin is detected. Clear RXEDGIF by writing a “1” to the SCIASR1 SCI alternative status register 1.

### **5.3.2.7 BERRIF Description**

The BERRIF interrupt is set when a mismatch between the transmitted and the received data in a single wire application like LIN was detected. Clear BERRIF by writing a “1” to the SCIASR1 SCI alternative status register 1. This flag is also cleared if the bit error detect feature is disabled.

### **5.3.2.8 BKDIF Description**

The BKDIF interrupt is set when a break signal was received. Clear BKDIF by writing a “1” to the SCIASR1 SCI alternative status register 1. This flag is also cleared if break detect feature is disabled.

## **5.3.3 Recovery from Wait Mode**

The SCI interrupt request can be used to bring the CPU out of wait mode.

### 5.3.4 Recovery from STOP mode

An active edge on the receive input can be used to bring the CPU out of STOP mode.





**FINAL PAGE OF  
54  
PAGES**