Product Preview

32 Kb I²C CMOS Serial EEPROM

Description

The CAT24C32B is a 32 Kb CMOS Serial EEPROM device, internally organized as 4096 words of 8 bits each.

It features a 32-byte page write buffer and supports the Standard (100 kHz), Fast (400 kHz) and Fast-Plus (1 MHz) I²C protocol.

External address pins make it possible to address up to eight CAT24C32B devices on the same bus.

Features

- Supports Standard, Fast and Fast–Plus I²C Protocol
- 1.55 V to 5.5 V Supply Voltage Range
- 32-Byte Page Write Buffer
- Fast Write Time (4 ms max)
- Hardware Write Protection for Entire Memory
- Schmitt Triggers and Noise Suppression Filters on I²C Bus Inputs (SCL and SDA)
- Low Power CMOS Technology
- 1,000,000 Program/Erase Cycles
- 100 Year Data Retention
- Industrial and Extended Temperature Range
- PDIP, SOIC, TSSOP, TDFN, UDFN 8-lead, and TSOP 5-lead Packages
- This Device is Pb–Free, Halogen Free/BFR Free, and RoHS Compliant

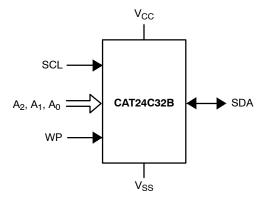


Figure 1. Functional Symbol

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SOIC-8 W SUFFIX CASE 751BD UDFN-8 HU4 SUFFIX CASE 517AZ

-8 TDFN-8* FFIX VP2 SUFFIX 7AZ CASE 511AK





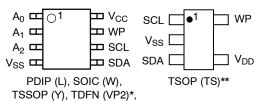


PDIP-8 L SUFFIX CASE 646AA

TSSOP-8 Y SUFFIX CASE 948AL

TSOP-5** TS SUFFIX CASE 483

PIN CONFIGURATIONS (Top Views)



For the location of Pin 1, please consult the corresponding package drawing.

* Not recommended for new designs.

UDFN (HU3*, HU4)

** Responds only to Slave Address A2 A1 A0 = 000

PIN FUNCTION

Pin Name	Function	
A ₀ , A ₁ , A ₂	Device Address	
SDA	Serial Data	
SCL	Serial Clock	
WP	Write Protect	
V _{CC}	Power Supply	
V _{SS}	Ground	

ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 14 of this data sheet.

Table 1. ABSOLUTE MAXIMUM RATINGS

Parameters	Ratings	Units
Storage Temperature	-65 to +150	°C
Voltage on Any Pin with Respect to Ground (Note 1)	-0.5 to +6.5	V

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

1. The DC input voltage on any pin should not be lower than -0.5 V or higher than V_{CC} + 0.5 V. During transitions, the voltage on any pin may undershoot to no less than -1.5 V or overshoot to no more than V_{CC} + 1.5 V, for periods of less than 20 ns.

Table 2. RELIABILITY CHARACTERISTICS (Note 2)

Symbol	Parameter	Min	Units
N _{END} (Note 3)	Endurance	1,000,000	Program/Erase Cycles
T _{DR}	Data Retention	100	Years

These parameters are tested initially and after a design or process change that affects the parameter according to appropriate AEC-Q100 and JEDEC test methods.

Table 3. D.C. OPERATING CHARACTERISTICS

 $(V_{CC} = 1.8 \text{ V to } 5.5 \text{ V}, T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C} \text{ and } V_{CC} = 1.55 \text{ V to } 5.5 \text{ V}, T_A = -40^{\circ}\text{C to } +85^{\circ}\text{C}, \text{ unless otherwise specified.})$

Symbol	Parameter	Test Cond	itions	Min	Max	Units
I _{CCR}	Read Current	Read, f _{SCL} = 400 kHz			1	mA
I _{CCW}	Write Current	Write, f _{SCL} = 400 kHz			2	mA
I _{SB}	Standby Current	All I/O Pins at GND or V _{CC}	$T_A = -40$ °C to +85°C $V_{CC} \le 3.3 \text{ V}$		1	μΑ
			$T_A = -40^{\circ}\text{C to } +85^{\circ}\text{C}$ $V_{CC} > 3.3 \text{ V}$		3	
			$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$		5	1
ΙL	I/O Pin Leakage	Pin at GND or V _{CC}			2	μΑ
V _{IL1}	Input Low Voltage	$1.7 \text{ V} \le \text{V}_{CC} \le 5.5 \text{ V}$		-0.5	0.3 V _{CC}	V
V_{IL2}	Input Low Voltage	1.55 V ≤ V _{CC} < 1.7 V		-0.5	0.2 V _{CC}	V
V _{IH1}	Input High Voltage	$1.7 \text{ V} \le \text{V}_{CC} \le 5.5 \text{ V}$		0.7 V _{CC}	V _{CC} + 0.5	V
V _{IH2}	Input High Voltage	1.55 V ≤ V _{CC} < 1.7 V		0.8 V _{CC}	V _{CC} + 0.5	V
V _{OL1}	Output Low Voltage	$V_{CC} \ge 2.5 \text{ V}, I_{OL} = 6.0 \text{ mA}$			0.4	V
V _{OL2}	Output Low Voltage	V_{CC} < 2.5 V, I_{OL} = 2.0 mA			0.2	V

Table 4. PIN IMPEDANCE CHARACTERISTICS

 $(V_{CC} = 1.8 \text{ V to } 5.5 \text{ V}, T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$ and $V_{CC} = 1.55 \text{ V to } 5.5 \text{ V}, T_A = -40^{\circ}\text{C to } +85^{\circ}\text{C}$, unless otherwise specified.)

Symbol	Parameter	Conditions	Max	Units
C _{IN} (Note 4)	SDA I/O Pin Capacitance	V _{IN} = 0 V	8	pF
C _{IN} (Note 4)	Input Capacitance (other pins)	V _{IN} = 0 V	6	pF
I _{WP} , I _A	WP Input Current, Address Input	V _{IN} < V _{IH} , V _{CC} = 5.5 V	50	μΑ
(Note 5)	Current (A0, A1, A2)	V _{IN} < V _{IH} , V _{CC} = 3.3 V	35	
		V _{IN} < V _{IH} , V _{CC} = 1.8 V	25	
		V _{IN} > V _{IH}	2	

These parameters are tested initially and after a design or process change that affects the parameter according to appropriate AEC-Q100 and JEDEC test methods.

^{3.} Page Mode, V_{CC} = 5 V, 25°C.

^{5.} When not driven, the WP, A0, A1 and A2 pins are pulled down to GND internally. For improved noise immunity, the internal pull–down is relatively strong; therefore the external driver must be able to supply the pull–down current when attempting to drive the input HIGH. To conserve power, as the input level exceeds the trip point of the CMOS input buffer (~ 0.5 x V_{CC}), the strong pull–down reverts to a weak current source.

Table 5. A.C. CHARACTERISTICS

 $(V_{CC} = 1.8 \text{ V to } 5.5 \text{ V}, T_A = -40^{\circ}\text{C to } + 125^{\circ}\text{C and } V_{CC} = 1.55 \text{ V to } 5.5 \text{ V}, T_A = -40^{\circ}\text{C to } + 85^{\circ}\text{C.}) \text{ (Note 6)}$

			ndard 5 V – 5.5 V	_	ast 55 V – 5.5 V		-Plus 3 V - 5.5 V	
Symbol	Parameter	Min	Max	Min	Max	Min	Max	Units
F _{SCL}	Clock Frequency		100		400		1,000	kHz
t _{HD:STA}	START Condition Hold Time	4		0.6		0.25		μs
t _{LOW}	Low Period of SCL Clock	4.7		1.3		0.45		μs
t _{HIGH}	High Period of SCL Clock	4		0.6		0.40		μs
t _{SU:STA}	START Condition Setup Time	4.7		0.6		0.25		μs
t _{HD:DAT}	Data In Hold Time	0		0		0		μs
t _{SU:DAT}	Data In Setup Time	250		100		50		ns
t _R (Note 7)	SDA and SCL Rise Time		1,000		300		100	ns
t _F (Note 7)	SDA and SCL Fall Time		300		300		100	ns
tsu:sto	STOP Condition Setup Time	4		0.6		0.25		μs
t _{BUF}	Bus Free Time Between STOP and START	4.7		1.3		0.5		μs
t _{AA}	SCL Low to Data Out Valid		3.5		0.9		0.40	μs
t _{DH}	Data Out Hold Time	100		100		50		ns
T _i (Note 7)	Noise Pulse Filtered at SCL and SDA Inputs		50		50		50	ns
t _{SU:WP}	WP Setup Time	0		0		0		μs
t _{HD:WP}	WP Hold Time	2.5		2.5		1		μs
twR	Write Cycle Time		4		4		4	ms
t _{PU} (Notes 7, 8)	Power-up to Ready Mode		0.35		0.35		0.35	ms

Table 6. A.C. TEST CONDITIONS

Input Levels	0.2 x V _{CC} to 0.8 x V _{CC}
Input Rise and Fall Times	≤ 50 ns
Input Reference Levels	0.3 x V _{CC} , 0.7 x V _{CC}
Output Reference Levels	0.5 x V _{CC}
Output Load	Current Source: I_{OL} = 6 mA (V_{CC} \geq 2.5 V); I_{OL} = 2 mA (V_{CC} < 2.5 V); C_L = 100 pF

^{6.} Test conditions according to "A.C. Test Conditions" table.
7. Tested initially and after a design or process change that affects this parameter.
8. t_{PU} is the delay between the time V_{CC} is stable and the device is ready to accept commands.

Power-On Reset (POR)

Each CAT24C32B incorporates Power-On Reset (POR) circuitry which protects the internal logic against powering up in the wrong state. The device will power up into Standby mode after V_{CC} exceeds the POR trigger level and will power down into Reset mode when V_{CC} drops below the POR trigger level. This bi-directional POR behavior protects the device against 'brown-out' failure following a temporary loss of power.

Pin Description

SCL: The Serial Clock input pin accepts the clock signal generated by the Master.

SDA: The Serial Data I/O pin accepts input data and delivers output data. In transmit mode, this pin is open drain. Data is acquired on the positive edge, and is delivered on the negative edge of SCL.

 A_0 , A_1 and A_2 : The Address inputs set the device address that must be matched by the corresponding Slave address bits. The Address inputs are hard-wired HIGH or LOW allowing for up to eight devices to be used (cascaded) on the same bus. When left floating, these pins are pulled LOW internally.

WP: When pulled HIGH, the Write Protect input pin inhibits all write operations. When left floating, this pin is pulled LOW internally.

Functional Description

The CAT24C32B supports the Inter-Integrated Circuit (I²C) Bus protocol. The protocol relies on the use of a Master device, which provides the clock and directs bus traffic, and Slave devices which execute requests. The CAT24C32B operates as a Slave device. Both Master and Slave can transmit or receive, but only the Master can assign those roles.

I²C Bus Protocol

The 2-wire I²C bus consists of two lines, SCL and SDA, connected to the V_{CC} supply via pull-up resistors. The Master provides the clock to the SCL line, and either the Master or the Slaves drive the SDA line. A '0' is transmitted by pulling a line LOW and a '1' by letting it stay HIGH. Data transfer may be initiated only when the bus is not busy (see A.C. Characteristics). During data transfer, SDA must remain stable while SCL is HIGH.

START/STOP Condition

An SDA transition while SCL is HIGH creates a START or STOP condition (Figure 2). The START consists of a HIGH to LOW SDA transition, while SCL is HIGH. Absent the START, a Slave will not respond to the Master. The STOP completes all commands, and consists of a LOW to HIGH SDA transition, while SCL is HIGH.

Device Addressing

The Master addresses a Slave by creating a START condition and then broadcasting an 8-bit Slave address. For the CAT24C32B, the first four bits of the Slave address are set to 1010 (Ah); the next three bits, A_2 , A_1 and A_0 , must match the logic state of the similarly named input pins. The R/\overline{W} bit tells the Slave whether the Master intends to read (1) or write (0) data (Figure 3).

Acknowledge

During the 9th clock cycle following every byte sent to the bus, the transmitter releases the SDA line, allowing the receiver to respond. The receiver then either acknowledges (ACK) by pulling SDA LOW, or does not acknowledge (NoACK) by letting SDA stay HIGH (Figure 4). Bus timing is illustrated in Figure 5.

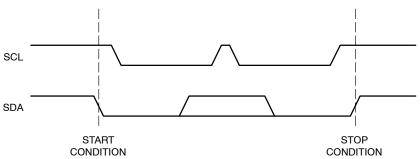


Figure 2. Start/Stop Timing

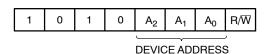


Figure 3. Slave Address Bits

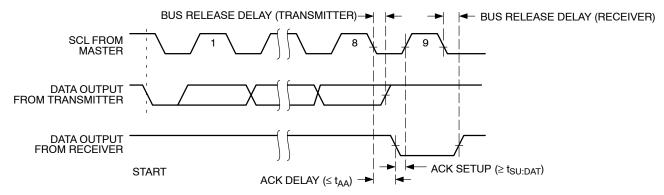


Figure 4. Acknowledge Timing

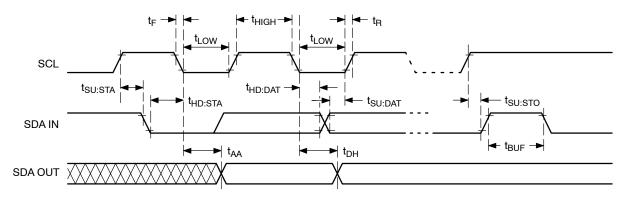


Figure 5. Bus Timing

WRITE OPERATIONS

Byte Write

To write data to memory, the Master creates a START condition on the bus and then broadcasts a Slave address with the R/\overline{W} bit set to '0'. The Master then sends two address bytes and a data byte and concludes the session by creating a STOP condition on the bus. The Slave responds with ACK after every byte sent by the Master (Figure 6). The STOP starts the internal Write cycle, and while this operation is in progress (t_{WR}), the SDA output is tri-stated and the Slave does not acknowledge the Master (Figure 7).

Page Write

The Byte Write operation can be expanded to Page Write, by sending more than one data byte to the Slave before issuing the STOP condition (Figure 8). Up to 32 distinct data bytes can be loaded into the internal Page Write Buffer starting at the address provided by the Master. The page address is latched, and as long as the Master keeps sending data, the internal byte address is incremented up to the end of page, where it then wraps around (within the page). New data can therefore replace data loaded earlier. Following the STOP, data loaded during the Page Write session will be written to memory in a single internal Write cycle (twR).

Acknowledge Polling

As soon (and as long) as internal Write is in progress, the Slave will not acknowledge the Master. This feature enables the Master to immediately follow-up with a new Read or Write request, rather than wait for the maximum specified Write time (t_{WR}) to elapse. Upon receiving a NoACK response from the Slave, the Master simply repeats the request until the Slave responds with ACK.

Hardware Write Protection

With the WP pin held HIGH, the entire memory is protected against Write operations. If the WP pin is left floating or is grounded, it has no impact on the Write operation. The state of the WP pin is strobed on the last falling edge of SCL immediately preceding the 1st data byte (Figure 9). If the WP pin is HIGH during the strobe interval, the Slave will not acknowledge the data byte and the Write request will be rejected.

Delivery State

The CAT24C32B is shipped erased, i.e., all bytes are FFh.

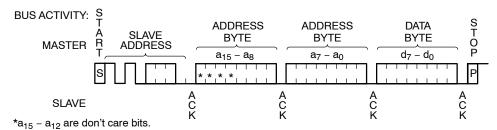


Figure 6. Byte Write Sequence

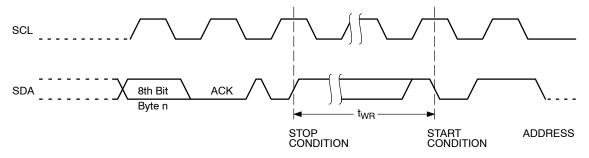


Figure 7. Write Cycle Timing

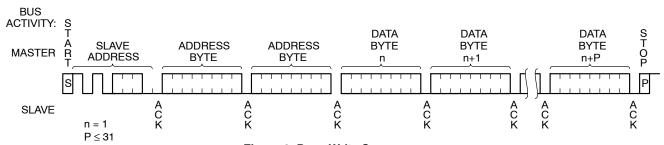


Figure 8. Page Write Sequence

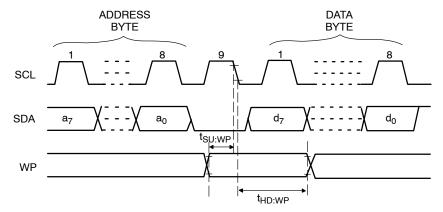


Figure 9. WP Timing

READ OPERATIONS

Immediate Read

To read data from memory, the Master creates a START condition on the bus and then broadcasts a Slave address with the R/\overline{W} bit set to '1'. The Slave responds with ACK and starts shifting out data residing at the current address. After receiving the data, the Master responds with NoACK and terminates the session by creating a STOP condition on the bus (Figure 10). The Slave then returns to Standby mode.

Selective Read

To read data residing at a specific address, the selected address must first be loaded into the internal address register. This is done by starting a Byte Write sequence, whereby the Master creates a START condition, then broadcasts a Slave address with the R/\overline{W} bit set to '0' and then sends two address bytes to the Slave. Rather than completing the Byte

Write sequence by sending data, the Master then creates a START condition and broadcasts a Slave address with the R/\overline{W} bit set to '1'. The Slave responds with ACK after every byte sent by the Master and then sends out data residing at the selected address. After receiving the data, the Master responds with NoACK and then terminates the session by creating a STOP condition on the bus (Figure 11).

Sequential Read

If, after receiving data sent by the Slave, the Master responds with ACK, then the Slave will continue transmitting until the Master responds with NoACK followed by STOP (Figure 12). During Sequential Read the internal byte address is automatically incremented up to the end of memory, where it then wraps around to the beginning of memory.

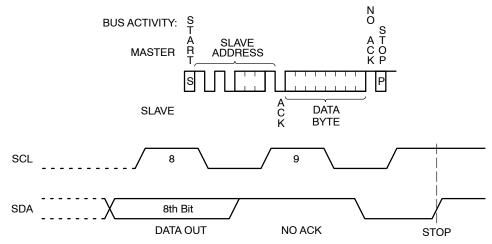


Figure 10. Immediate Read Sequence and Timing

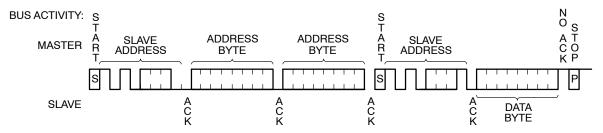


Figure 11. Selective Read Sequence

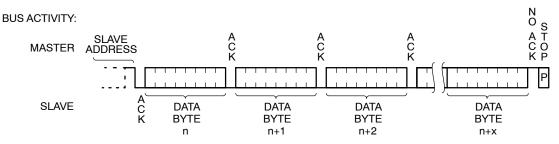
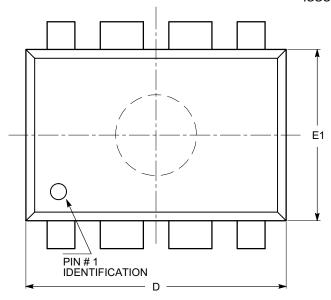


Figure 12. Sequential Read Sequence

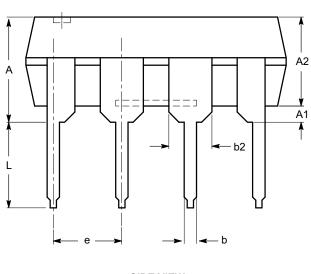
PACKAGE DIMENSIONS

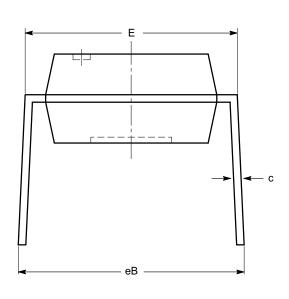
PDIP-8, 300 mils CASE 646AA-01 ISSUE A



SYMBOL	MIN	NOM	MAX
Α			5.33
A1	0.38		
A2	2.92	3.30	4.95
b	0.36	0.46	0.56
b2	1.14	1.52	1.78
С	0.20	0.25	0.36
D	9.02	9.27	10.16
Е	7.62	7.87	8.25
E1	6.10	6.35	7.11
е		2.54 BSC	
eB	7.87		10.92
L	2.92	3.30	3.80

TOP VIEW





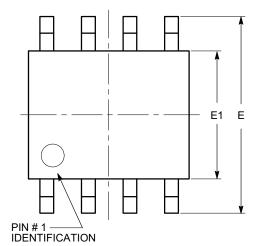
SIDE VIEW

END VIEW

- (1) All dimensions are in millimeters.
- (2) Complies with JEDEC MS-001.

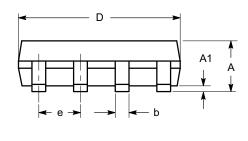
PACKAGE DIMENSIONS

SOIC 8, 150 mils CASE 751BD-01 ISSUE O

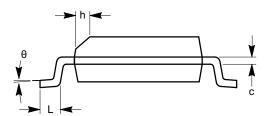


SYMBOL	MIN	NOM	MAX
А	1.35		1.75
A1	0.10		0.25
b	0.33		0.51
С	0.19		0.25
D	4.80		5.00
E	5.80		6.20
E1	3.80		4.00
е		1.27 BSC	
h	0.25		0.50
L	0.40		1.27
θ	0°		8°

TOP VIEW



SIDE VIEW

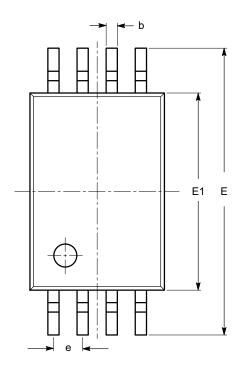


END VIEW

- (1) All dimensions are in millimeters. Angles in degrees.(2) Complies with JEDEC MS-012.

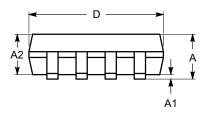
PACKAGE DIMENSIONS

TSSOP8, 4.4x3 CASE 948AL-01 ISSUE O

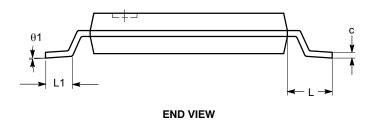


SYMBOL	MIN	NOM	MAX		
Α			1.20		
A1	0.05		0.15		
A2	0.80	0.90	1.05		
b	0.19		0.30		
С	0.09		0.20		
D	2.90	3.00	3.10		
Е	6.30	6.40	6.50		
E1	4.30	4.40	4.50		
е	0.65 BSC				
L	1.00 REF				
L1	0.50	0.60	0.75		
θ	0°		8°		







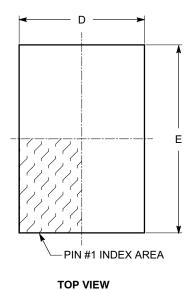


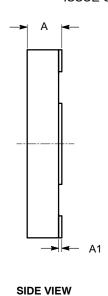
- (1) All dimensions are in millimeters. Angles in degrees.(2) Complies with JEDEC MO-153.

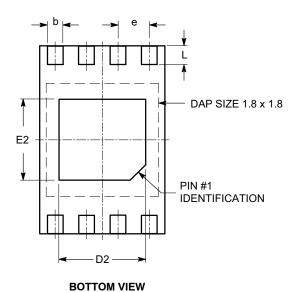
PACKAGE DIMENSIONS

UDFN8, 2x3 EXTENDED PAD

CASE 517AZ-01 ISSUE O



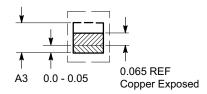




SYMBOL	MIN	NOM	MAX	
Α	0.45	0.50	0.55	
A1	0.00	0.02	0.05	
A3	0.127 REF			
b	0.20	0.25	0.30	
D	1.95	2.00	2.05	
D2	1.35	1.40	1.45	
Е	2.95	3.00	3.05	
E2	1.25	1.30	1.35	
е	0.50 REF			
L	0.25	0.30	0.35	

0.065 REF DETAIL A A3 A

FRONT VIEW

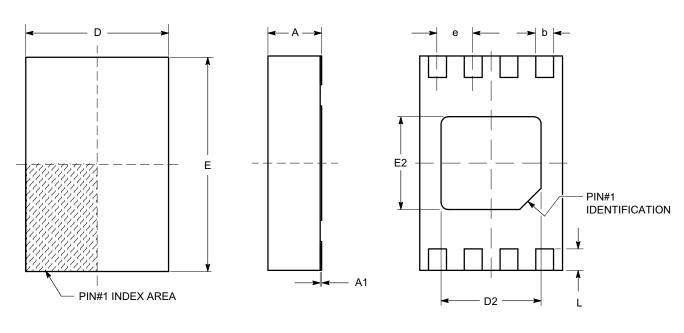


DETAIL A

- (1) All dimensions are in millimeters.
- (2) Refer JEDEC MO-236/MO-252.

PACKAGE DIMENSIONS

TDFN8, 2x3 CASE 511AK-01 ISSUE A



SIDE VIEW

SYMBOL	MIN	NOM	MAX	
Α	0.70	0.75	0.80	
A1	0.00	0.02	0.05	
A2	0.45	0.55	0.65	
A3	0.20 REF			
b	0.20	0.25	0.30	
D	1.90	2.00	2.10	
D2	1.30	1.40	1.50	
Е	2.90	3.00	3.10	
E2	1.20	1.30	1.40	
е	0.50 TYP			
L	0.20	0.30	0.40	

Α2

FRONT VIEW

BOTTOM VIEW

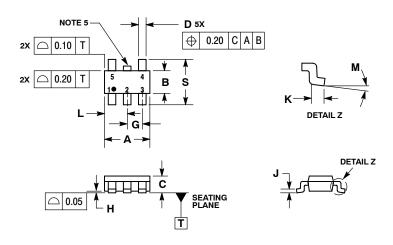
Notes:

- (1) All dimensions are in millimeters.(2) Complies with JEDEC MO-229.

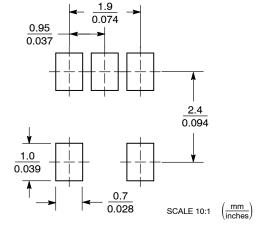
TOP VIEW

PACKAGE DIMENSIONS

TSOP-5 CASE 483-02 ISSUE H



SOLDERING FOOTPRINT*



*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

NOTES:

- NOTES:

 1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.

 2. CONTROLLING DIMENSION: MILLIMETERS.

 3. MAXIMUM LEAD THICKNESS INCLUDES LEAD FINISH THICKNESS. MINIMUM LEAD THICKNESS IS THE MINIMUM THICKNESS.

 CE BASE MATERIAL
- OF BASE MATERIAL.

 4. DIMENSIONS A AND B DO NOT INCLUDE MOLD FLASH, PROTRUSIONS, OR GATE BURRS.
- SURRS.

 5. OPTIONAL CONSTRUCTION: AN
 ADDITIONAL TRIMMED LEAD IS ALLOWED
 IN THIS LOCATION. TRIMMED LEAD NOT TO
 EXTEND MORE THAN 0.2 FROM BODY.

	MILLIMETERS					
DIM	MIN	MAX				
Α	3.00 BSC					
В	1.50 BSC					
С	0.90	1.10				
D	0.25	0.50				
G	0.95 BSC					
Η	0.01	0.10				
7	0.10	0.26				
K	0.20	0.60				
L	1.25	1.55				
М	0°	10°				
ď	2.50	3.00				

Ordering Information

Device Order Number	Specific Device Marking	Package Type	Temperature Range	Wire	Lead Finish	Shipping
CAT24C32BLE-G	24C32G	PDIP-8	E = Extended (-40°C to +125°C)	Au	NiPdAu	Tube, 50 Units / Tube
CAT24C32BLI-G	24C32G	PDIP-8	I = Industrial (-40°C to +85°C)	Au	NiPdAu	Tube, 50 Units / Tube
CAT24C32BWE-G	24C32G	SOIC-8, JEDEC	E = Extended (-40°C to +125°C)	Au	NiPdAu	Tube, 100 Units / Tube
CAT24C32BWI-G	24C32G	SOIC-8, JEDEC	I = Industrial (-40°C to +85°C)	Au	NiPdAu	Tube, 100 Units / Tube
CAT24C32BWE-GT3	24C32G	SOIC-8, JEDEC	E = Extended (-40°C to +125°C)	Au	NiPdAu	Tape & Reel, 3,000 Units / Reel
CAT24C32BWE-KT3	24C32G	SOIC-8, JEDEC	E = Extended (-40°C to +125°C)	Cu	NiPdAu	Tape & Reel, 3,000 Units / Reel
CAT24C32BWI-GT3	24C32G	SOIC-8, JEDEC	I = Industrial (-40°C to +85°C)	Au	NiPdAu	Tape & Reel, 3,000 Units / Reel
CAT24C32BWI-KT3	24C32G	SOIC-8, JEDEC	I = Industrial (-40°C to +85°C)	Cu	NiPdAu	Tape & Reel, 3,000 Units / Reel
CAT24C32BYE-G	C32G	TSSOP-8	E = Extended (-40°C to +125°C)	Au	NiPdAu	Tube, 100 Units / Tube
CAT24C32BYI-G	C32G	TSSOP-8	I = Industrial (-40°C to +85°C)	Au	NiPdAu	Tube, 100 Units / Tube
CAT24C32BYE-GT3	C32G	TSSOP-8	E = Extended (-40°C to +125°C)	Au	NiPdAu	Tape & Reel, 3,000 Units / Reel
CAT24C32BYE-KT3	C32G	TSSOP-8	E = Extended (-40°C to +125°C)	Cu	NiPdAu	Tape & Reel, 3,000 Units / Reel
CAT24C32BYI-GT3	C32G	TSSOP-8	I = Industrial (-40°C to +85°C)	Au	NiPdAu	Tape & Reel, 3,000 Units / Reel
CAT24C32BYI-KT3	C32G	TSSOP-8	I = Industrial (-40°C to +85°C)	Cu	NiPdAu	Tape & Reel, 3,000 Units / Reel
CAT24C32BHU4E-GT3	C5L	UDFN8	E = Extended (-40°C to +125°C)	Au	NiPdAu	Tape & Reel, 3,000 Units / Reel
CAT24C32BHU4I-GT3	C5L	UDFN8	I = Industrial (-40°C to +85°C)	Au	NiPdAu	Tape & Reel, 3,000 Units / Reel
CAT24C32BTSI-T3	C5G	TSOP-5	I = Industrial (-40°C to +85°C)	Au	Matte-Tin	Tape & Reel, 3,000 Units / Reel
CAT24C32BVP2I-GT3 (Note 11)	C5J	TDFN-8	I = Industrial (-40°C to +85°C)	Au	NiPdAu	Tape & Reel, 3,000 Units / Reel

^{9.} All packages are RoHS-compliant (Lead-free, Halogen-free).

^{10.} The standard lead finish is NiPdAu.

11. The TDFN 2 x 3 x 0.75 mm (VP2) package is not recommended for new designs. Please replace with UDFN 2 x 3 x 0.5 mm (HU4).

^{12.} For additional package and temperature options, please contact your nearest ON Semiconductor Sales office.

13. For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

^{14.} For detailed information and a breakdown of device nomenclature and numbering systems, please see the ON Semiconductor Device Nomenclature document, TND310/D, available at www.onsemi.com

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