# EEPROM Serial 32-Kb I<sup>2</sup>C Automotive Grade 1 in Wettable Flank UDFN-8 Package

#### Description

The NV24C32 is a EEPROM Serial 32–Kb I<sup>2</sup>C Automotive Grade 1 devices, internally organized as 4096 words of 8 bits each.

It features a 32-byte page write buffer and supports the Standard (100 kHz) and Fast (400 kHz) I<sup>2</sup>C protocol.

External address pins make it possible to address up to eight NV24C32 devices on the same bus.

#### **Features**

- Automotive AEC-Q100 Grade 1 (-40°C to +125°C) Qualified
- Supports Standard and Fast I<sup>2</sup>C Protocol
- 2.5 V to 5.5 V Supply Voltage Range
- 32-Byte Page Write Buffer
- Hardware Write Protection for Entire Memory
- NV Prefix for Automotive and Other Applications Requiring Site and Change Control
- Schmitt Triggers and Noise Suppression Filters on I<sup>2</sup>C Bus Inputs (SCL and SDA)
- Low Power CMOS Technology
- 1,000,000 Program/Erase Cycles
- 100 Year Data Retention
- UDFN-8 Wettable Flank Package
- This Device is Pb–Free, Halogen Free/BFR Free, and RoHS Compliant

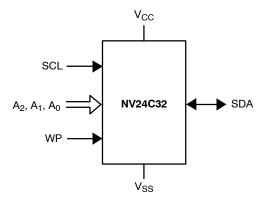


Figure 1. Functional Symbol



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UDFN8 MU SUFFIX CASE 517DH

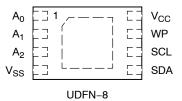
#### **MARKING DIAGRAM**



C5W = Specific Device Code A = Assembly Location

WL = Wafer Lot Y = Year W = Work Week ■ Pb-Free Package

#### **PIN CONFIGURATION**



#### **PIN FUNCTION**

Pin Name	Function	
A0, A1, A2	Device Address Input	
SDA	Serial Data Input/Output	
SCL	Serial Clock Input	
WP	Write Protect Input	
V <sub>CC</sub>	Power Supply	
V <sub>SS</sub>	Ground	

#### **ORDERING INFORMATION**

See detailed ordering and shipping information in the package dimensions section on page 8 of this data sheet.

**Table 1. ABSOLUTE MAXIMUM RATINGS** 

Parameters	Ratings	Units
Storage Temperature	−65 to +150	°C
Voltage on any Pin with Respect to Ground (Note 1)	-0.5 to +6.5	V

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

Table 2. RELIABILITY CHARACTERISTICS (Note 2)

Symbol	Parameter	Min	Units
N <sub>END</sub> (Note 3)	Endurance	1,000,000	Program/Erase Cycles
T <sub>DR</sub>	Data Retention	100	Years

These parameters are tested initially and after a design or process change that affects the parameter according to appropriate AEC-Q100 and JEDEC test methods.

Table 3. D.C. OPERATING CHARACTERISTICS ( $V_{CC} = 2.5 \text{ V}$  to 5.5 V,  $T_A = -40 ^{\circ}\text{C}$  to  $+125 ^{\circ}\text{C}$ , unless otherwise specified.)

Symbol	Parameter	Test Conditions		Min	Max	Units
I <sub>CCR</sub>	Read Current	Read, f <sub>SCL</sub> = 400 kHz			1	mA
I <sub>CCW</sub>	Write Current	Write, f <sub>SCL</sub> = 400 kHz			2	mA
I <sub>SB</sub>	Standby Current	All I/O Pins at GND or V <sub>CC</sub>	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$		5	μΑ
ΙL	I/O Pin Leakage	Pin at GND or V <sub>CC</sub>			2	μΑ
V <sub>IL</sub>	Input Low Voltage			-0.5	0.3 x V <sub>CC</sub>	V
V <sub>IH</sub>	Input High Voltage	A <sub>0</sub> , A <sub>1</sub> , A <sub>2</sub> and WP		0.7 x V <sub>CC</sub>	V <sub>CC</sub> + 0.5	V
		SCL and SDA		0.7 x V <sub>CC</sub>	5.5	
V <sub>OL</sub>	Output Low Voltage	$V_{CC} > 2.5 \text{ V}, I_{OL} = 3 \text{ mA}$			0.4	V

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

Table 4. PIN IMPEDANCE CHARACTERISTICS (V<sub>CC</sub> = 2.5 V to 5.5 V, T<sub>A</sub> = -40°C to +125°C, unless otherwise specified.)

Symbol	Parameter	Conditions	Max	Units
C <sub>IN</sub> (Note 4)	SDA I/O Pin Capacitance	V <sub>IN</sub> = 0 V, T <sub>A</sub> = 25°C, V <sub>CC</sub> = 5.0 V	8	pF
C <sub>IN</sub> (Note 4)	Input Capacitance (other pins)	V <sub>IN</sub> = 0 V, T <sub>A</sub> = 25°C, V <sub>CC</sub> = 5.0 V	6	pF
I <sub>WP</sub> (Note 5)	WP Input Current	V <sub>IN</sub> < V <sub>IH</sub> , V <sub>CC</sub> = 5.5 V	130	μΑ
		V <sub>IN</sub> < V <sub>IH</sub> , V <sub>CC</sub> = 3.3 V	120	1
		V <sub>IN</sub> < V <sub>IH</sub> , V <sub>CC</sub> = 2.5 V	80	
		$V_{IN} < V_{IH}$	2	
I <sub>A</sub> (Note 5)	Address Input Current	V <sub>IN</sub> < V <sub>IH</sub> , V <sub>CC</sub> = 5.5 V	50	μΑ
	(A0, A1, A2) Product Rev F	V <sub>IN</sub> < V <sub>IH</sub> , V <sub>CC</sub> = 3.3 V	35	
		$V_{IN} < V_{IH}, V_{CC} = 2.5 V$	25	
		$V_{IN} > V_{IH}$	2	

These parameters are tested initially and after a design or process change that affects the parameter according to appropriate AEC-Q100 and JEDEC test methods.

During input transitions, voltage undershoot on any pin should not exceed –1 V for more than 20 ns. Voltage overshoot on pins A<sub>0</sub>, A<sub>1</sub>, A<sub>2</sub> and WP should not exceed V<sub>CC</sub> + 1 V for more than 20 ns, while voltage on the I<sup>2</sup>C bus pins, SCL and SDA, should not exceed the absolute maximum ratings, irrespective of V<sub>CC</sub>.

<sup>3.</sup> Page Mode,  $V_{CC} = 5 \text{ V}$ ,  $25^{\circ}\text{C}$ .

<sup>5.</sup> When not driven, the WP, A0, A1 and A2 pins are pulled down to GND internally. For improved noise immunity, the internal pull-down is relatively strong; therefore the external driver must be able to supply the pull-down current when attempting to drive the input HIGH. To conserve power, as the input level exceeds the trip point of the CMOS input buffer (~ 0.5 x V<sub>CC</sub>), the strong pull-down reverts to a weak current source.

Table 5. A.C. CHARACTERISTICS ( $V_{CC} = 2.5 \text{ V}$  to 5.5 V,  $T_A = -40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ , unless otherwise specified.) (Note 6)

		Stan	dard	Fa	ast	
Symbol	Parameter		Max	Min	Max	Units
F <sub>SCL</sub>	Clock Frequency		100		400	kHz
t <sub>HD:STA</sub>	START Condition Hold Time	4		0.6		μs
t <sub>LOW</sub>	Low Period of SCL Clock	4.7		1.3		μs
t <sub>HIGH</sub>	High Period of SCL Clock	4		0.6		μs
t <sub>SU:STA</sub>	START Condition Setup Time	4.7		0.6		μs
t <sub>HD:DAT</sub>	Data In Hold Time	0		0		μs
t <sub>SU:DAT</sub>	Data In Setup Time	250		100		ns
t <sub>R</sub>	SDA and SCL Rise Time		1000		300	ns
t <sub>F</sub> (Note 6)	SDA and SCL Fall Time		300		300	ns
t <sub>SU:STO</sub>	STOP Condition Setup Time	4		0.6		μs
t <sub>BUF</sub>	Bus Free Time Between STOP and START	4.7		1.3		μs
t <sub>AA</sub>	SCL Low to Data Out Valid		3.5		0.9	μs
t <sub>DH</sub>	Data Out Hold Time	100		100		ns
T <sub>i</sub> (Note 6)	Noise Pulse Filtered at SCL and SDA Inputs		100		100	ns
t <sub>SU:WP</sub>	WP Setup Time	0		0		μs
t <sub>HD:WP</sub>	WP Hold Time	2.5		2.5		μs
t <sub>WR</sub>	Write Cycle Time		5		5	ms
t <sub>PU</sub> (Notes 7, 8)	Power-up to Ready Mode		1		1	ms

## Table 6. A.C. TEST CONDITIONS

Input Drive Levels	0.2 x V <sub>CC</sub> to 0.8 x V <sub>CC</sub>
Input Rise and Fall Time	≤ 50 ns
Input Reference Levels	0.3 x V <sub>CC</sub> , 0.7 x V <sub>CC</sub>
Output Reference Level	0.5 x V <sub>CC</sub>
Output Test Load	Current Source I <sub>OL</sub> = 3 mA; C <sub>L</sub> = 100 pF

<sup>6.</sup> Test conditions according to "AC Test Conditions" table.
7. Tested initially and after a design or process change that affects this parameter.
8. t<sub>PU</sub> is the delay between the time V<sub>CC</sub> is stable and the device is ready to accept commands.

#### Power-On Reset (POR)

Each NV24C32 incorporates Power-On Reset (POR) circuitry which protects the internal logic against powering up in the wrong state. The device will power up into Standby mode after  $V_{\rm CC}$  exceeds the POR trigger level and will power down into Reset mode when  $V_{\rm CC}$  drops below the POR trigger level. This bi-directional POR behavior protects the device against 'brown-out' failure following a temporary loss of power.

#### **Pin Description**

**SCL:** The Serial Clock input pin accepts the clock signal generated by the Master.

**SDA:** The Serial Data I/O pin accepts input data and delivers output data. In transmit mode, this pin is open drain. Data is acquired on the positive edge, and is delivered on the negative edge of SCL.

 $A_0$ ,  $A_1$  and  $A_2$ : The Address inputs set the device address that must be matched by the corresponding Slave address bits. The Address inputs are hard-wired HIGH or LOW allowing for up to eight devices to be used (cascaded) on the same bus. When left floating, these pins are pulled LOW internally.

**WP:** When pulled HIGH, the Write Protect input pin inhibits all write operations. When left floating, this pin is pulled LOW internally.

#### **Functional Description**

The NV24C32 supports the Inter-Integrated Circuit (I<sup>2</sup>C) Bus protocol. The protocol relies on the use of a Master device, which provides the clock and directs bus traffic, and Slave devices which execute requests. The NV24C32 operates as a Slave device. Both Master and Slave can transmit or receive, but only the Master can assign those roles.

#### I<sup>2</sup>C Bus Protocol

The 2-wire  $I^2C$  bus consists of two lines, SCL and SDA, connected to the  $V_{CC}$  supply via pull-up resistors. The Master provides the clock to the SCL line, and either the Master or the Slaves drive the SDA line. A '0' is transmitted by pulling a line LOW and a '1' by letting it stay HIGH. Data transfer may be initiated only when the bus is not busy (see A.C. Characteristics). During data transfer, SDA must remain stable while SCL is HIGH.

#### **START/STOP Condition**

An SDA transition while SCL is HIGH creates a START or STOP condition (Figure 2). The START consists of a HIGH to LOW SDA transition, while SCL is HIGH. Absent the START, a Slave will not respond to the Master. The STOP completes all commands, and consists of a LOW to HIGH SDA transition, while SCL is HIGH.

#### **Device Addressing**

The Master addresses a Slave by creating a START condition and then broadcasting an 8-bit Slave address. For the NV24C32, the first four bits of the Slave address are set to 1010 (Ah); the next three bits,  $A_2$ ,  $A_1$  and  $A_0$ , must match the logic state of the similarly named input pins. The R/W bit tells the Slave whether the Master intends to read (1) or write (0) data (Figure 3).

#### Acknowledge

During the 9<sup>th</sup> clock cycle following every byte sent to the bus, the transmitter releases the SDA line, allowing the receiver to respond. The receiver then either acknowledges (ACK) by pulling SDA LOW, or does not acknowledge (NoACK) by letting SDA stay HIGH (Figure 4). Bus timing is illustrated in Figure 5.

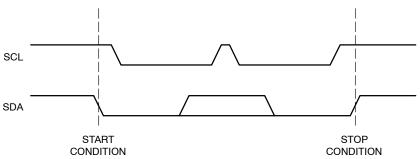


Figure 2. Start/Stop Timing

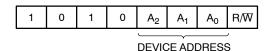


Figure 3. Slave Address Bits

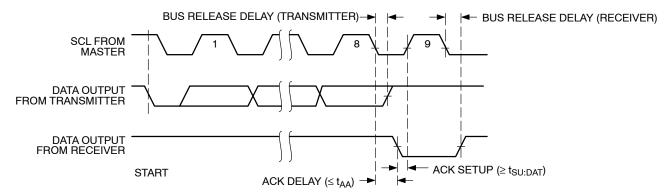


Figure 4. Acknowledge Timing

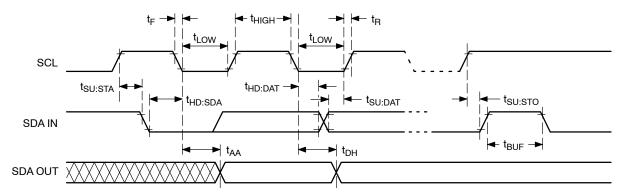


Figure 5. Bus Timing

#### **WRITE OPERATIONS**

#### **Byte Write**

To write data to memory, the Master creates a START condition on the bus and then broadcasts a Slave address with the  $R/\overline{W}$  bit set to '0'. The Master then sends two address bytes and a data byte and concludes the session by creating a STOP condition on the bus. The Slave responds with ACK after every byte sent by the Master (Figure 6). The STOP starts the internal Write cycle, and while this operation is in progress ( $t_{WR}$ ), the SDA output is tri-stated and the Slave does not acknowledge the Master (Figure 7).

#### **Page Write**

The Byte Write operation can be expanded to Page Write, by sending more than one data byte to the Slave before issuing the STOP condition (Figure 8). Up to 32 distinct data bytes can be loaded into the internal Page Write Buffer starting at the address provided by the Master. The page address is latched, and as long as the Master keeps sending data, the internal byte address is incremented up to the end of page, where it then wraps around (within the page). New data can therefore replace data loaded earlier. Following the STOP, data loaded during the Page Write session will be written to memory in a single internal Write cycle (t<sub>WR</sub>).

#### **Acknowledge Polling**

As soon (and as long) as internal Write is in progress, the Slave will not acknowledge the Master. This feature enables the Master to immediately follow-up with a new Read or Write request, rather than wait for the maximum specified Write time ( $t_{WR}$ ) to elapse. Upon receiving a NoACK response from the Slave, the Master simply repeats the request until the Slave responds with ACK.

#### **Hardware Write Protection**

With the WP pin held HIGH, the entire memory is protected against Write operations. If the WP pin is left floating or is grounded, it has no impact on the Write operation. The state of the WP pin is strobed on the last falling edge of SCL immediately preceding the 1<sup>st</sup> data byte (Figure 9). If the WP pin is HIGH during the strobe interval, the Slave will not acknowledge the data byte and the Write request will be rejected.

#### **Delivery State**

The NV24C32 is shipped erased, i.e., all bytes are FFh.

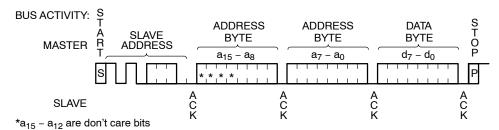


Figure 6. Byte Write Sequence

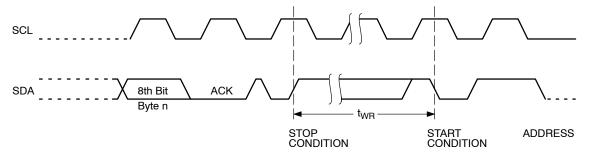
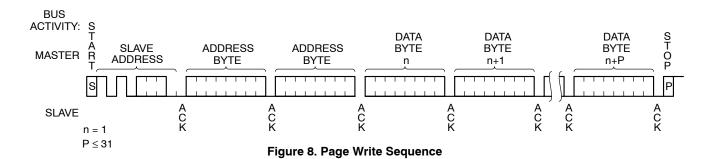


Figure 7. Write Cycle Timing



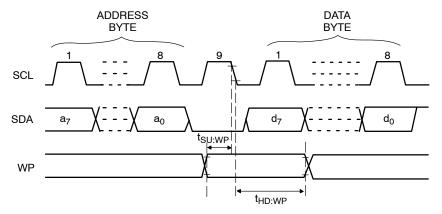


Figure 9. WP Timing

#### **READ OPERATIONS**

#### **Immediate Read**

To read data from memory, the Master creates a START condition on the bus and then broadcasts a Slave address with the  $R/\overline{W}$  bit set to '1'. The Slave responds with ACK and starts shifting out data residing at the current address. After receiving the data, the Master responds with NoACK and terminates the session by creating a STOP condition on the bus (Figure 10). The Slave then returns to Standby mode.

#### **Selective Read**

To read data residing at a specific address, the selected address must first be loaded into the internal address register. This is done by starting a Byte Write sequence, whereby the Master creates a START condition, then broadcasts a Slave address with the  $R/\overline{W}$  bit set to '0' and then sends two address bytes to the Slave. Rather than completing the Byte

Write sequence by sending data, the Master then creates a START condition and broadcasts a Slave address with the  $R/\overline{W}$  bit set to '1'. The Slave responds with ACK after every byte sent by the Master and then sends out data residing at the selected address. After receiving the data, the Master responds with NoACK and then terminates the session by creating a STOP condition on the bus (Figure 11).

#### **Sequential Read**

If, after receiving data sent by the Slave, the Master responds with ACK, then the Slave will continue transmitting until the Master responds with NoACK followed by STOP (Figure 12). During Sequential Read the internal byte address is automatically incremented up to the end of memory, where it then wraps around to the beginning of memory.

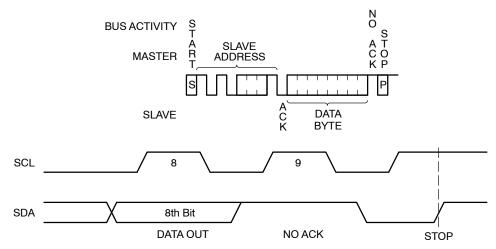


Figure 10. Immediate Read Sequence and Timing

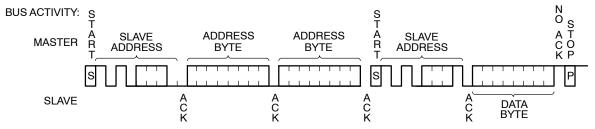


Figure 11. Selective Read Sequence

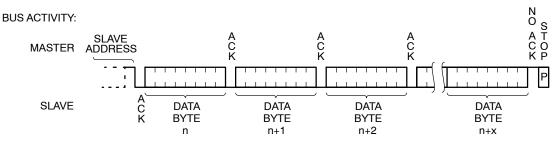


Figure 12. Sequential Read Sequence

#### **ORDERING INFORMATION**

Device Order Number	Specific Device Marking	Package Type	Temperature Range	Shipping <sup>†</sup>
NV24C32MUW3VTBG	C5W	UDFN-8 (2x3 mm) Wettable Flank	V = Auto Grade 1 (-40°C to +125°C)	Tape & Reel, 3,000 Units / Reel

<sup>†</sup>For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

ON Semiconductor is licensed by the Philips Corporation to carry the  $I^2C$  bus protocol.

<sup>9.</sup> All packages are RoHS-compliant (Lead-free, Halogen-free).

10. Please contact your nearest ON Semiconductor Sales office for availability.

11. Caution: The EEPROM devices delivered in WLCSP must never be exposed to ultraviolet light. When exposed to ultraviolet light the EEPROM cells lose their stored data.

С

PIN ONE INDICATOR

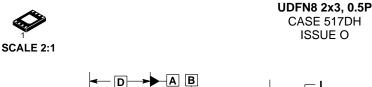
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NOTE 4

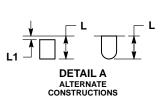
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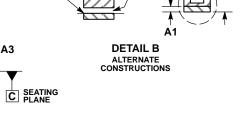
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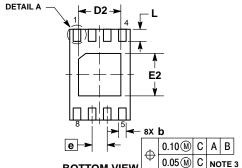


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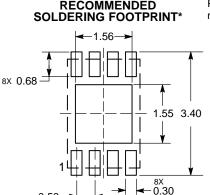






SIDE VIEW

# RECOMMENDED



#### \*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

DIMENSIONS: MILLIMETERS

0.50 → PITCH

DOCUMENT NUMBER:	98AON06579G	Electronic versions are uncontrolle	
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DESCRIPTION:	UDFN8 2X3, 0.5P		PAGE 1 OF 2

- NOTES:
  1. DIMENSIONING AND TOLERANCING PER
- ASME Y14.5M, 1994. CONTROLLING DIMENSION: MILLIMETERS.
- DIMENSION b APPLIES TO PLATED
   TERMINAL AND IS MEASURED BETWEEN
- 1.15 AND 0.25MM FROM THE TERMINAL TIP.
  COPLANARITY APPLIES TO THE EXPOSED
  PAD AS WELL AS THE TERMINALS.
  FOR DEVICE OPN CONTAINING W OPTION,
- DETAIL B ALTERNATE CONSTRUCTION IS NOT APPLICABLE.

	MILLIMETERS		
DIM	MIN	MAX	
Α	0.45	0.55	
A1	0.00	0.05	
A3	0.13	REF	
b	0.20	0.30	
D	2.00	BSC	
D2	1.30	1.50	
E	3.00	BSC	
E2	1.30	1.50	
е	0.50 BSC		
L	0.30	0.50	
L1	-	0.15	

#### **GENERIC MARKING DIAGRAM\***

XXXXX AWLYW.

XXXXX = Specific Device Code Α = Assembly Location

WL = Wafer Lot = Year

W = Work Week

= Pb-Free Package

\*This information is generic. Please refer to device data sheet for actual part marking. Pb-Free indicator, "G" or microdot " ■", may or may not be present.

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DOCUMENT	NUMBER:
98AON06579	G

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ISSUE	REVISION	DATE
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